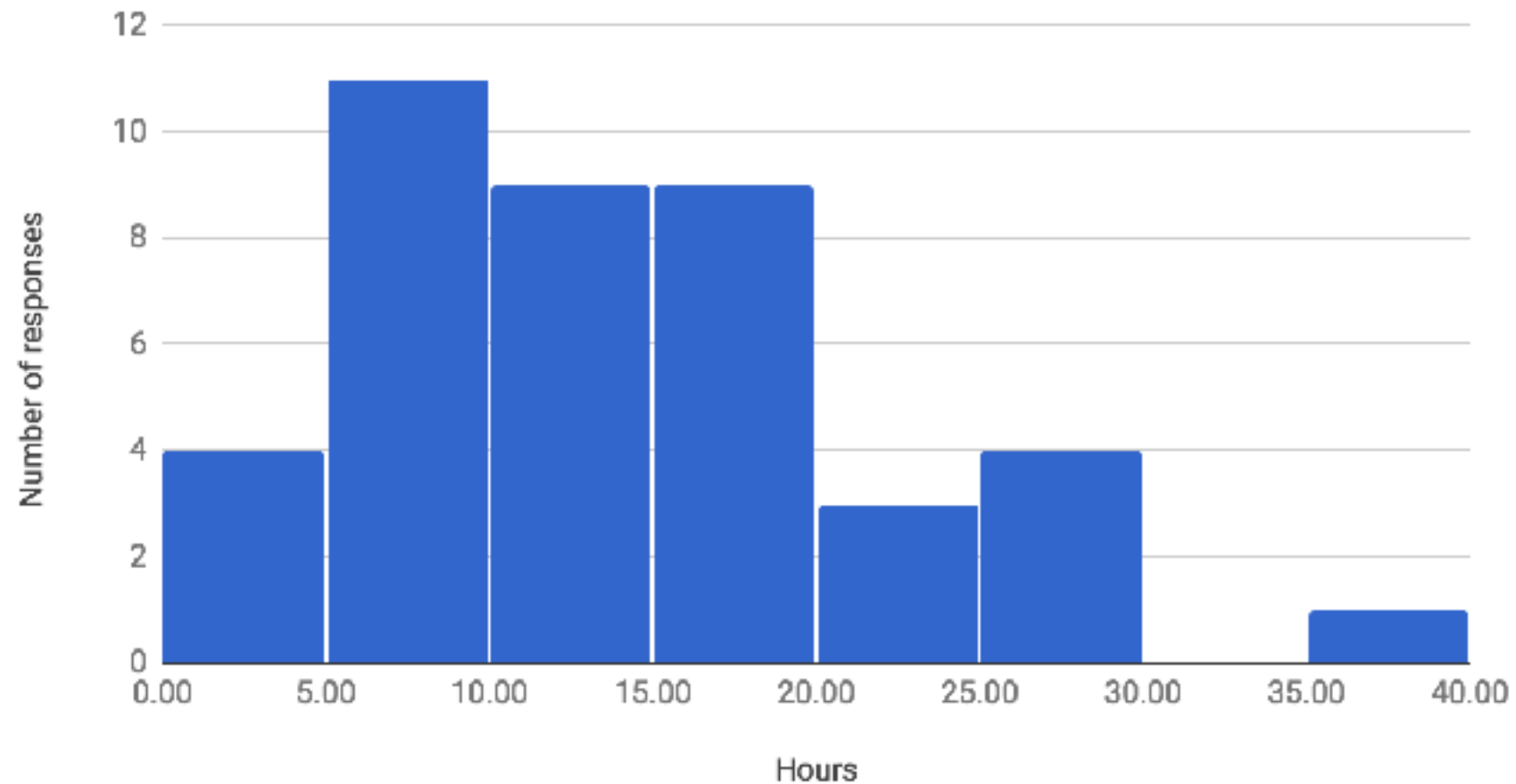


# **Clustering Part III: DP-means, CH index, hierarchical clustering**

George Chen

# HW1 Survey

Self-reported number of hours spent on HW1



**In comments, students asked for:**

More applications

More demos in class

Smaller datasets

More math

Less demos in class

Cover less topics

# Co-occurrence Analysis: Applications

- Turns out to have more applications that figuring out what Opec might be related to
- If you're an online store/retailer:  
anticipate *when* certain products are likely to be purchased/  
rented/consumed more
  - Products & dates
- If you have a bunch of physical stores:  
anticipate *where* certain products are likely to be purchased/  
rented/consumed more
  - Products & locations
- If you're the police department:  
create "heat map" of where different criminal activity occurs
  - Crime reports & locations

# Co-occurrence Analysis: Applications

- Turns out to have more applications that figuring out what Opec might be related to
- If you are interested in...
  - Examples of data to take advantage of:
    - data collected by your organization
    - social networks
    - news websites
    - blogs
  - Web scraping frameworks can be helpful:
    - Scrapy
    - Selenium (great with JavaScript-heavy pages)
- If you're the police department, create "heat map" of where different criminal activity occurs
  - Crime reports & locations

# Back to Clustering

***k*-means approximates  
(a special case of) learning GMM's.**

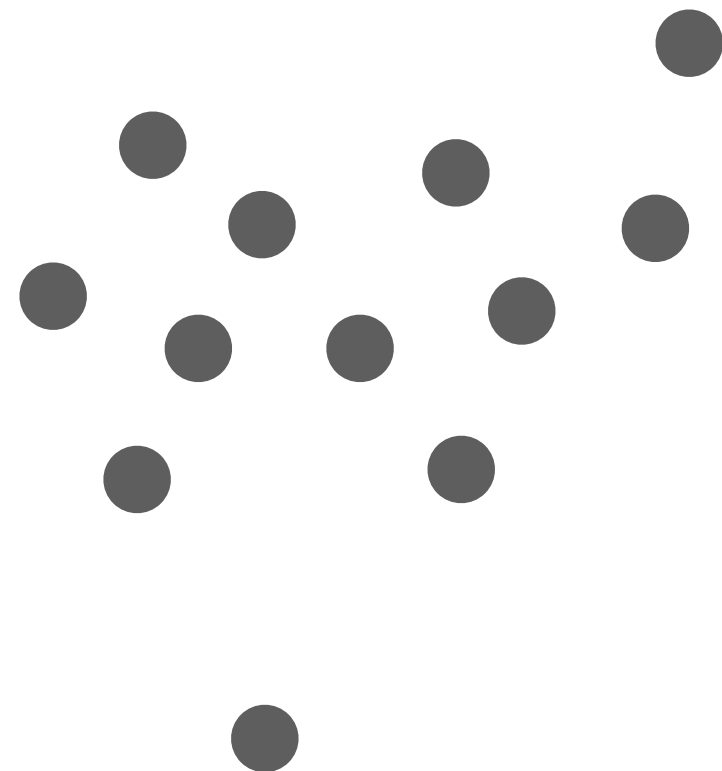
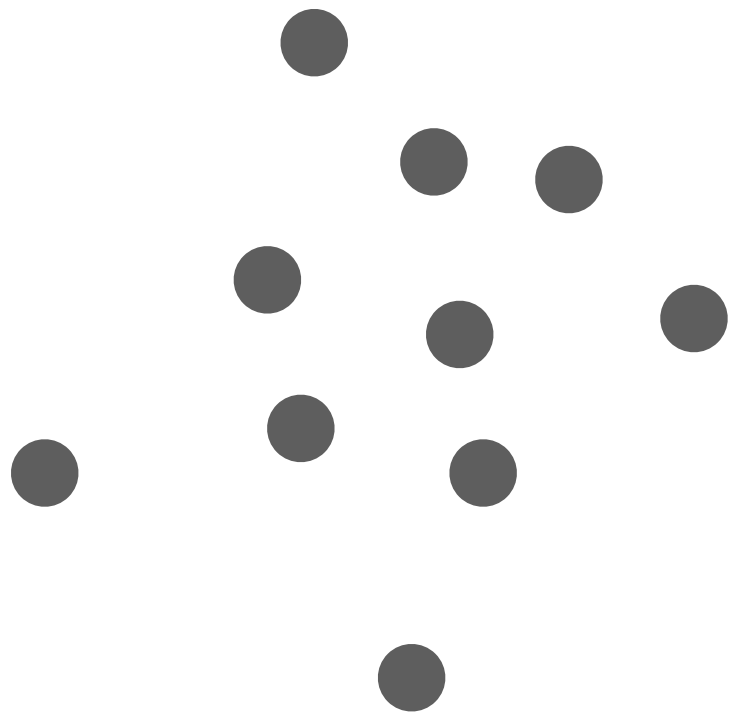
**What approximates learning DP-GMMs?**

This next algorithm will give you a sense of how we get around specifying the number of clusters directly

# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

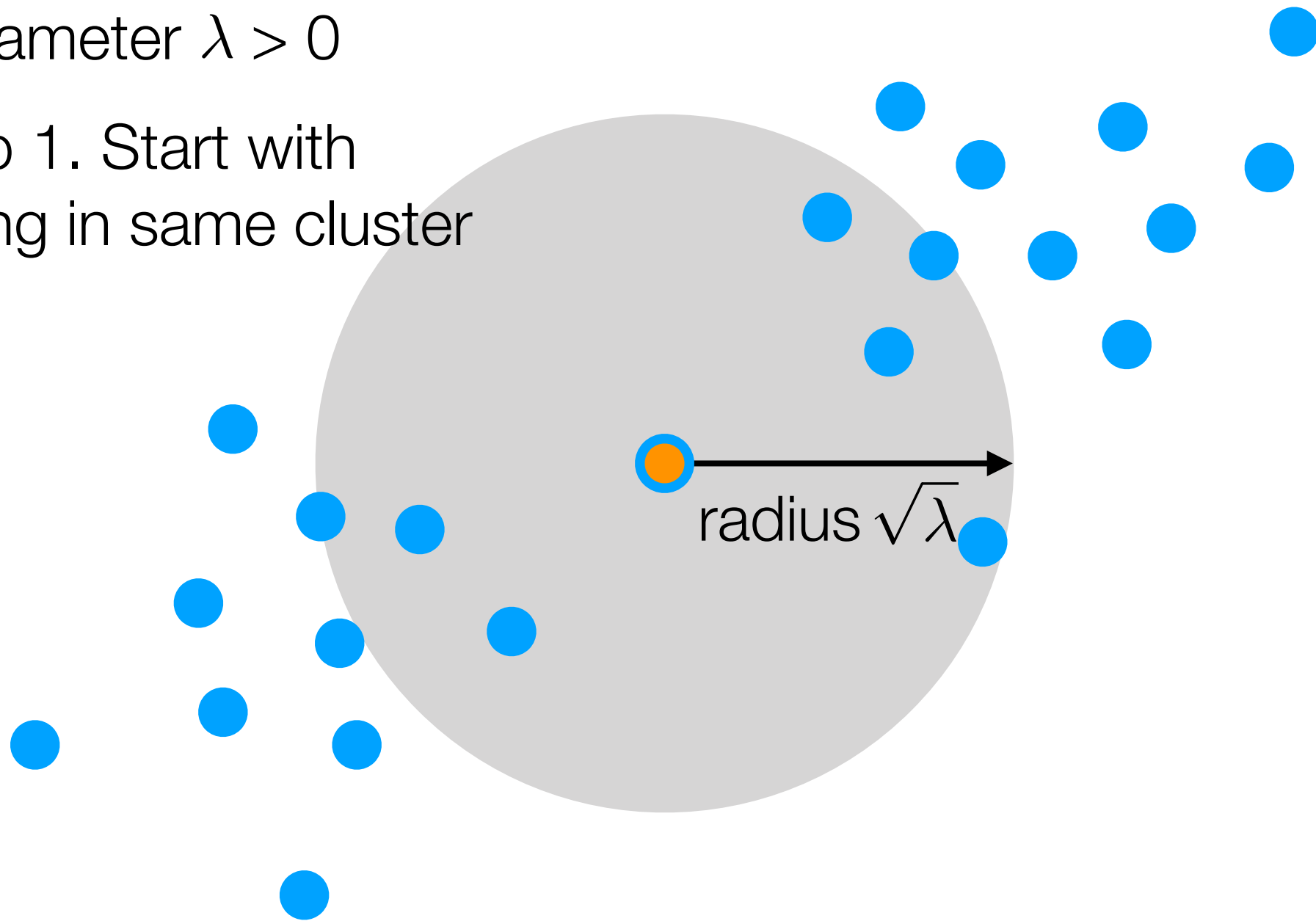
Step 1. Start with everything in same cluster



# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

Step 1. Start with everything in same cluster

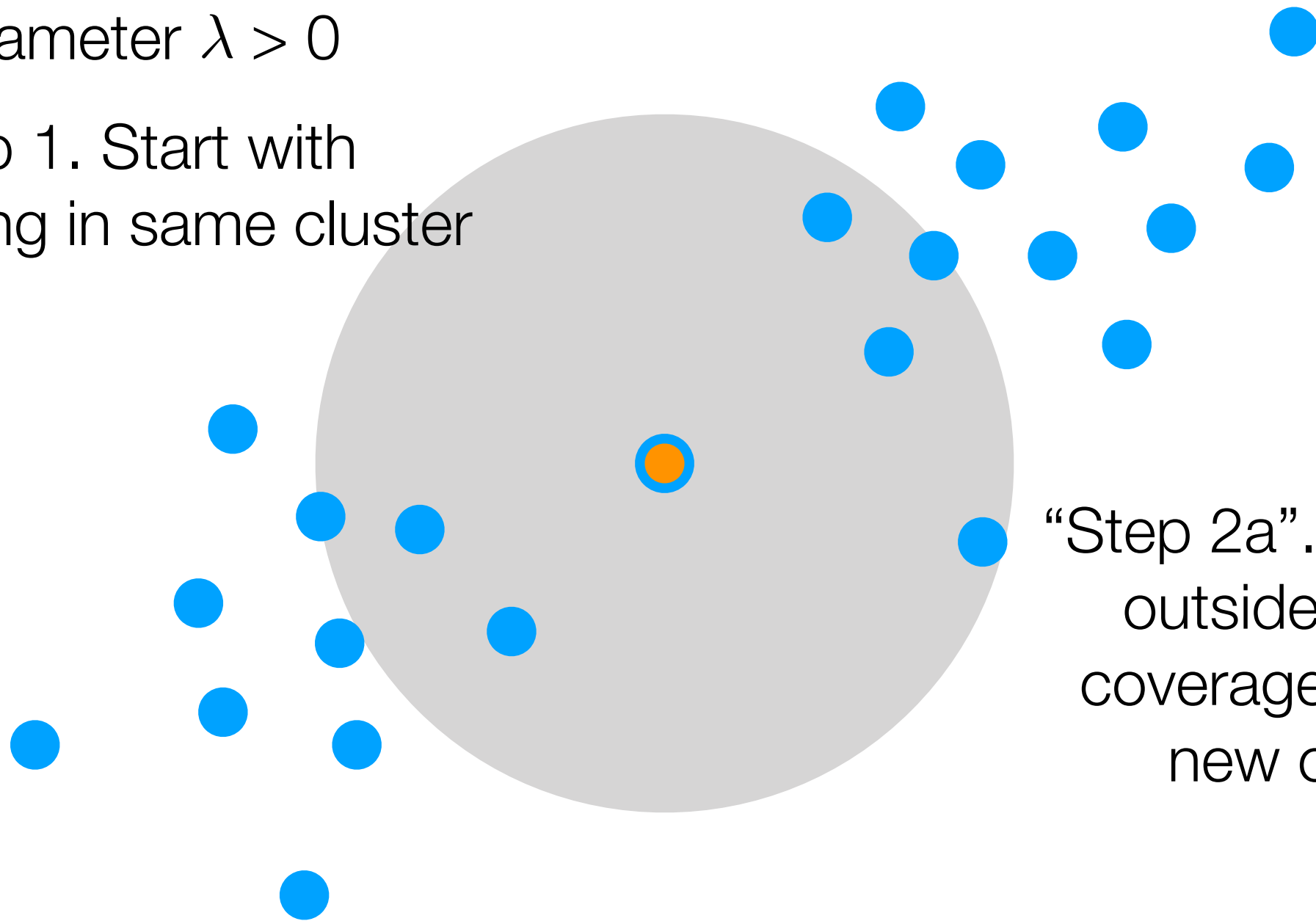




# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

Step 1. Start with everything in same cluster

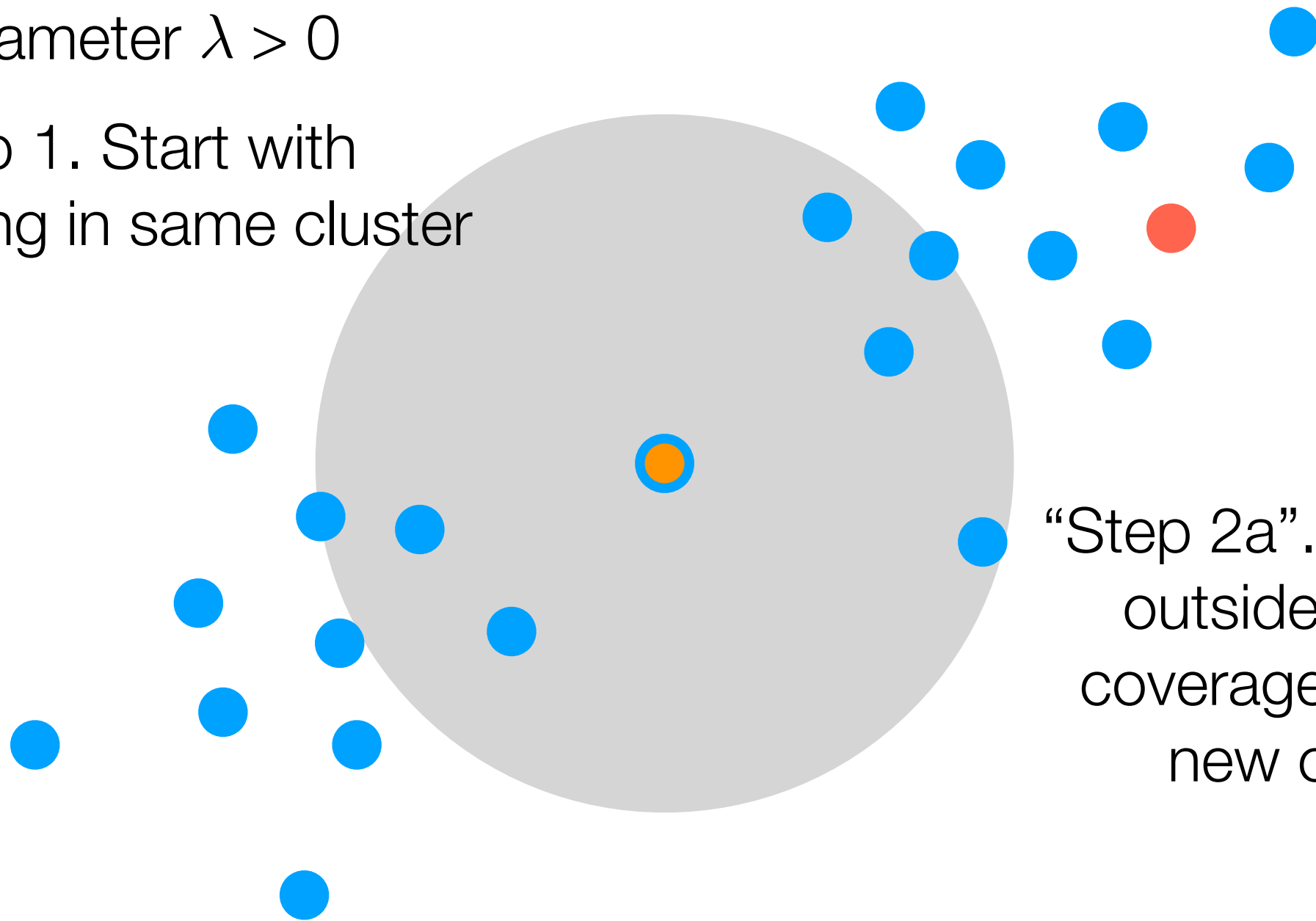


“Step 2a”. Pick point outside of gray coverage to make new cluster

# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

Step 1. Start with everything in same cluster

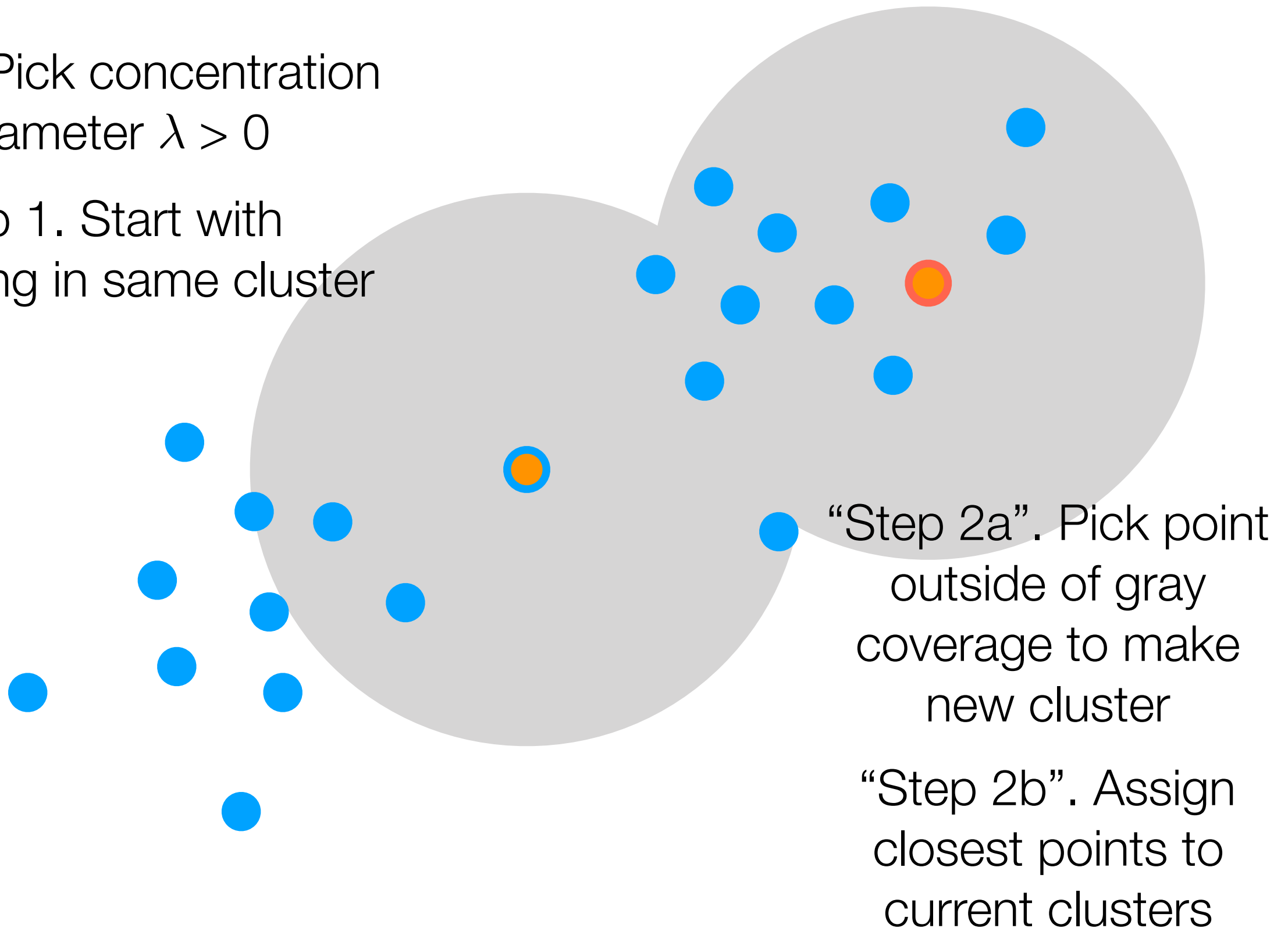


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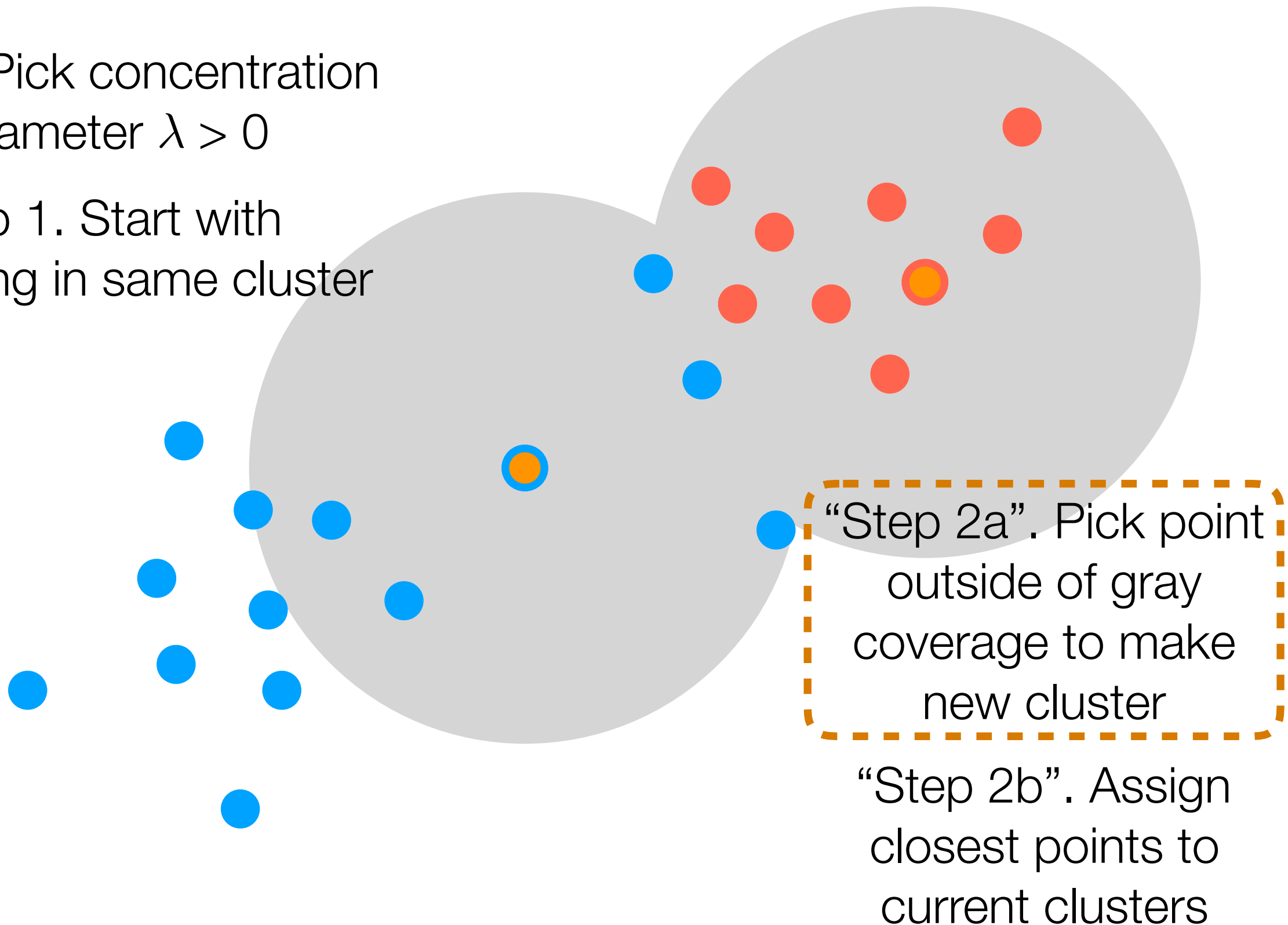
Step 1. Start with everything in same cluster



# DP-means

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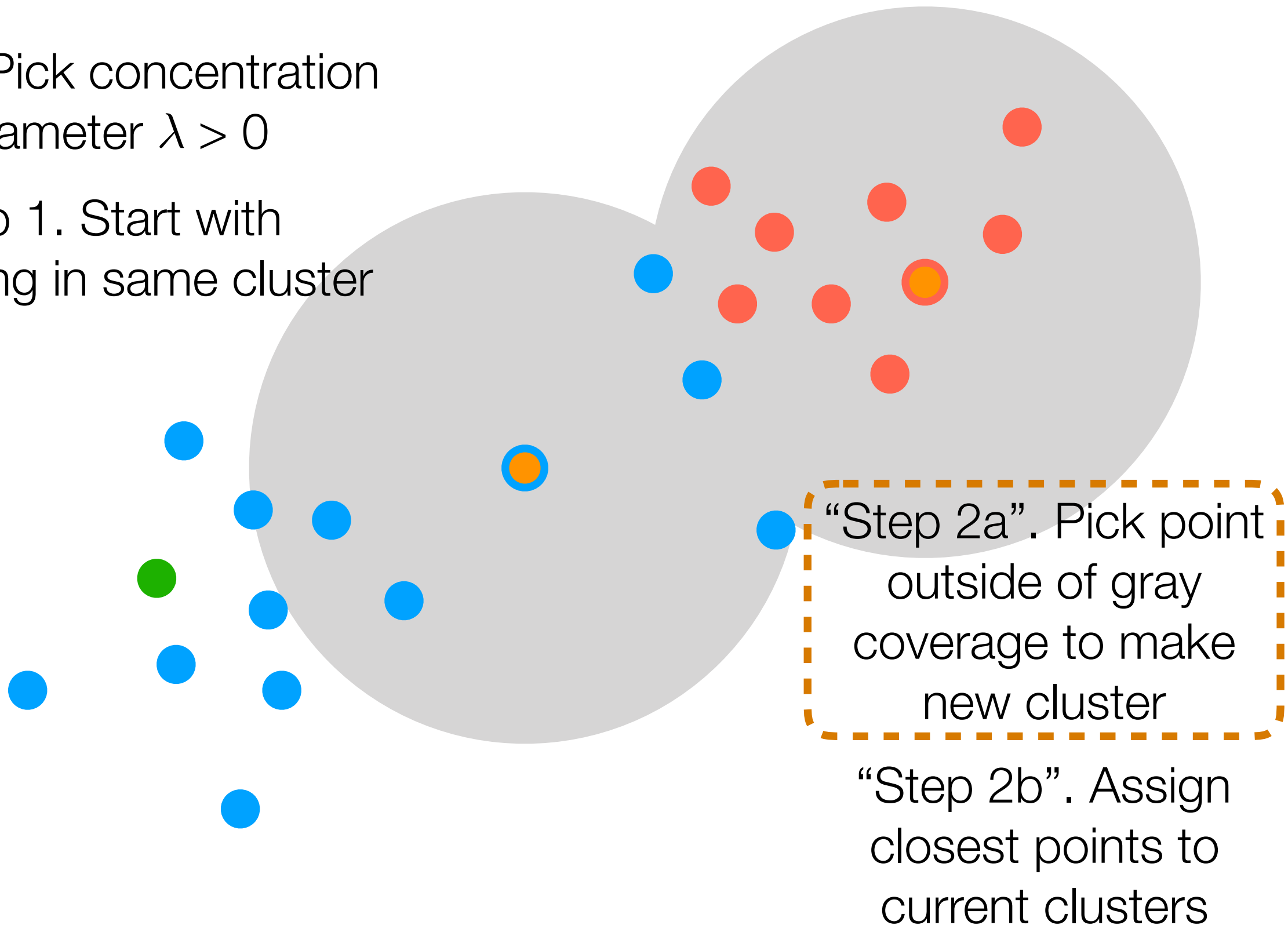
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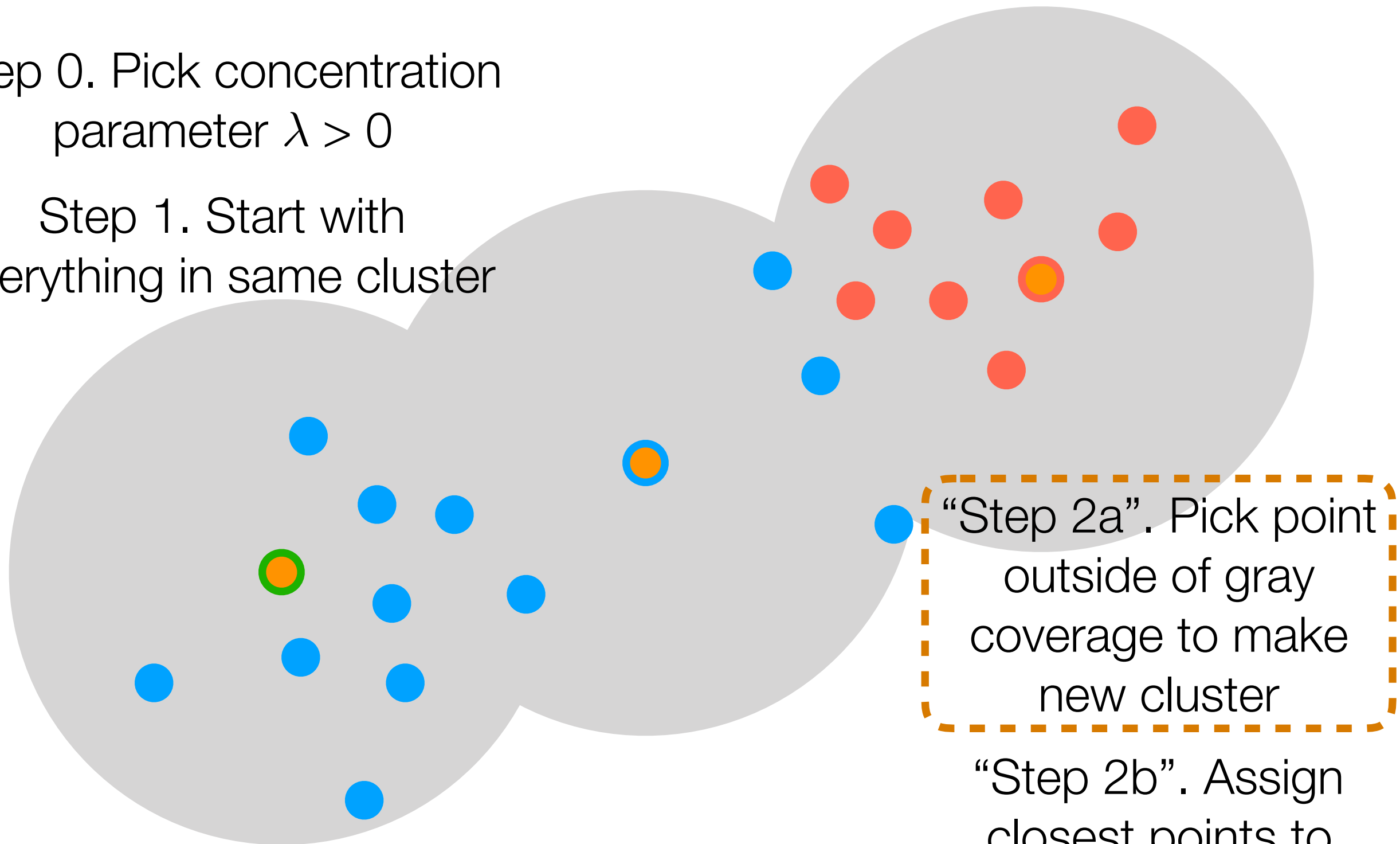
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# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

Step 1. Start with everything in same cluster

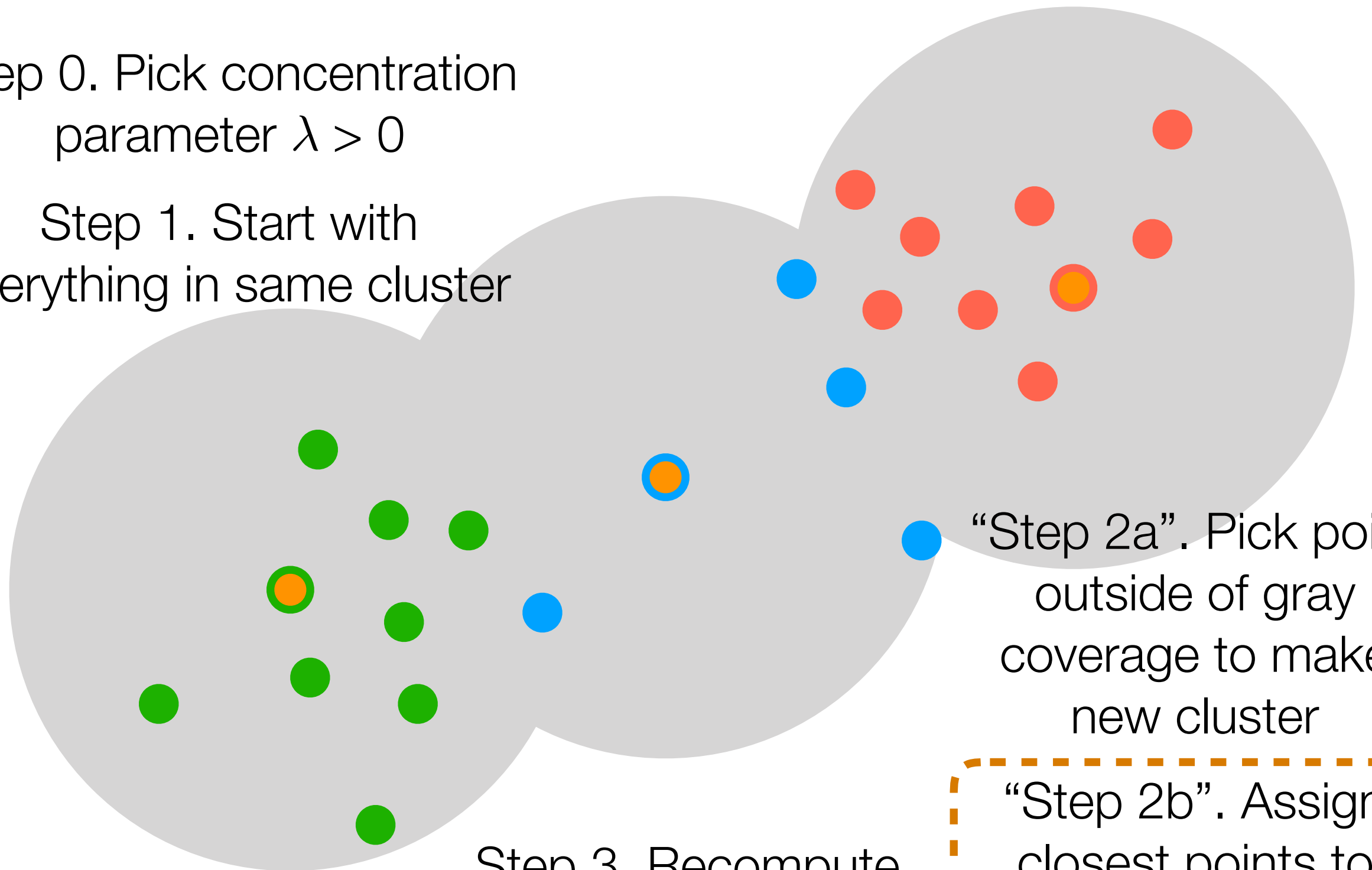


“Step 2b”. Assign closest points to current clusters

# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

Step 1. Start with everything in same cluster



“Step 2a”. Pick point outside of gray coverage to make new cluster

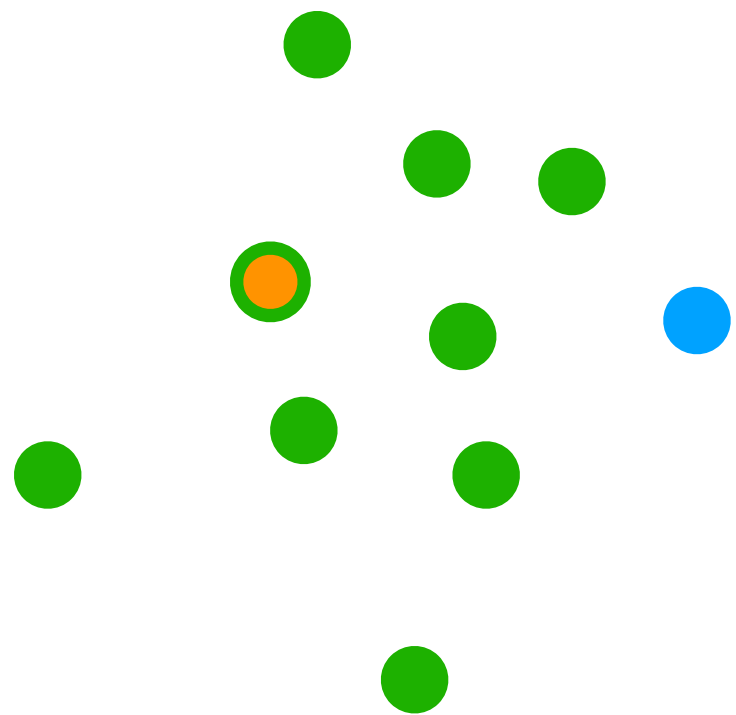
“Step 2b”. Assign closest points to current clusters

Step 3. Recompute cluster centers

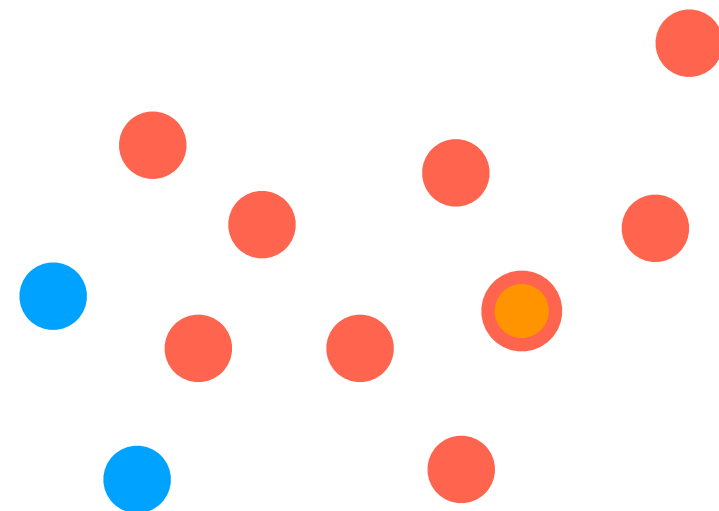
# DP-means

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Step 1. Start with everything in same cluster



Step 3. Recompute cluster centers



“Step 2a”. Pick point outside of gray coverage to make new cluster

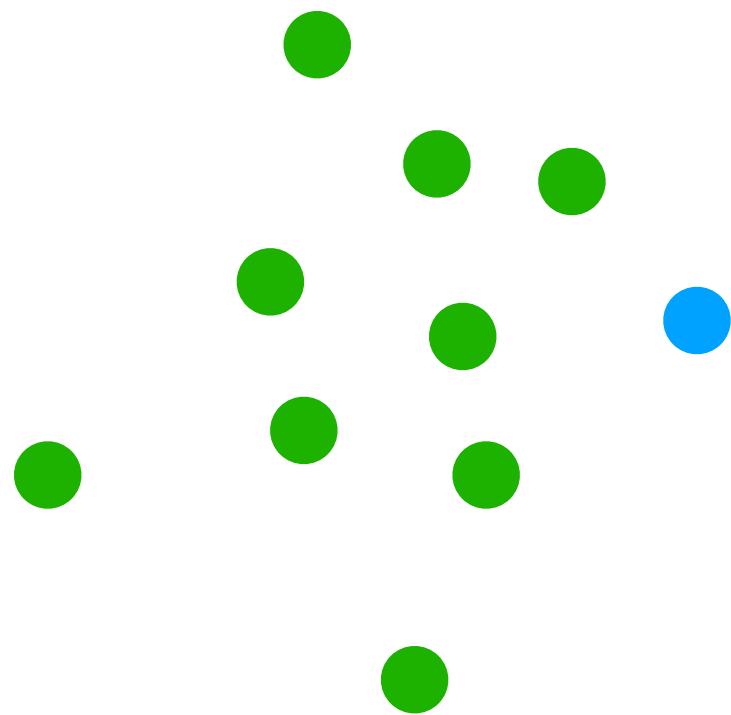
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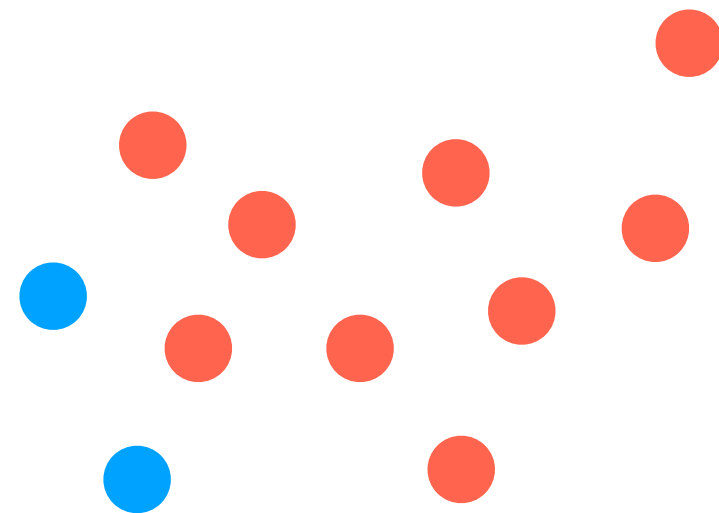
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Step 3. Recompute cluster centers



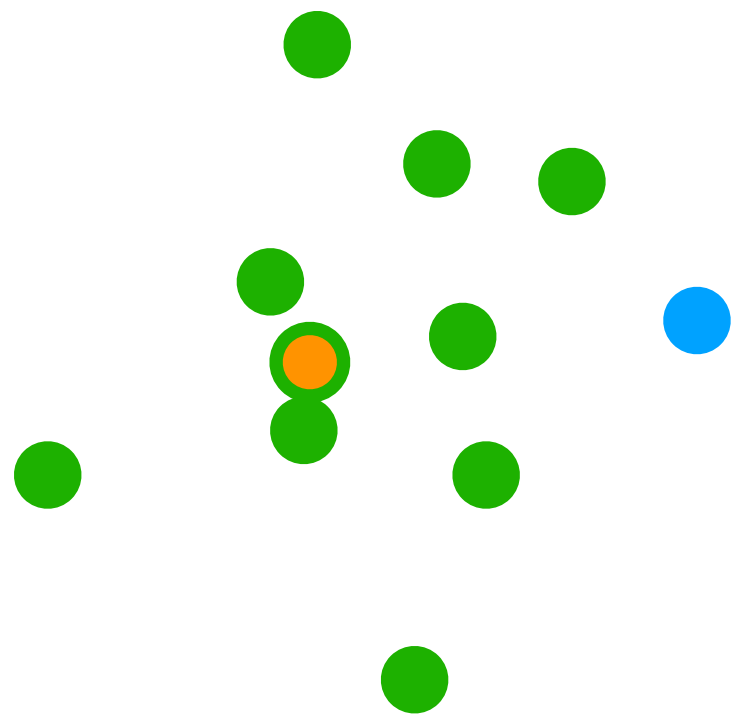
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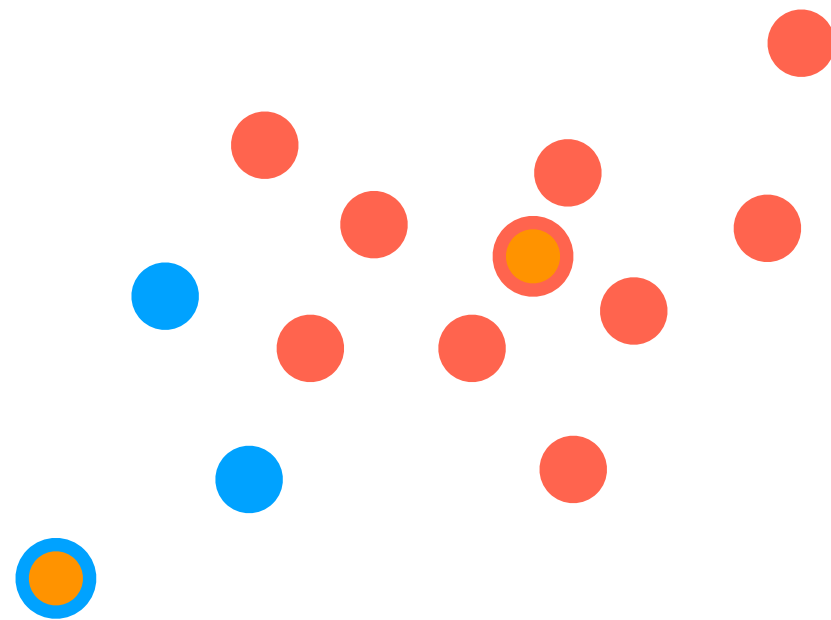
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Step 3. Recompute cluster centers



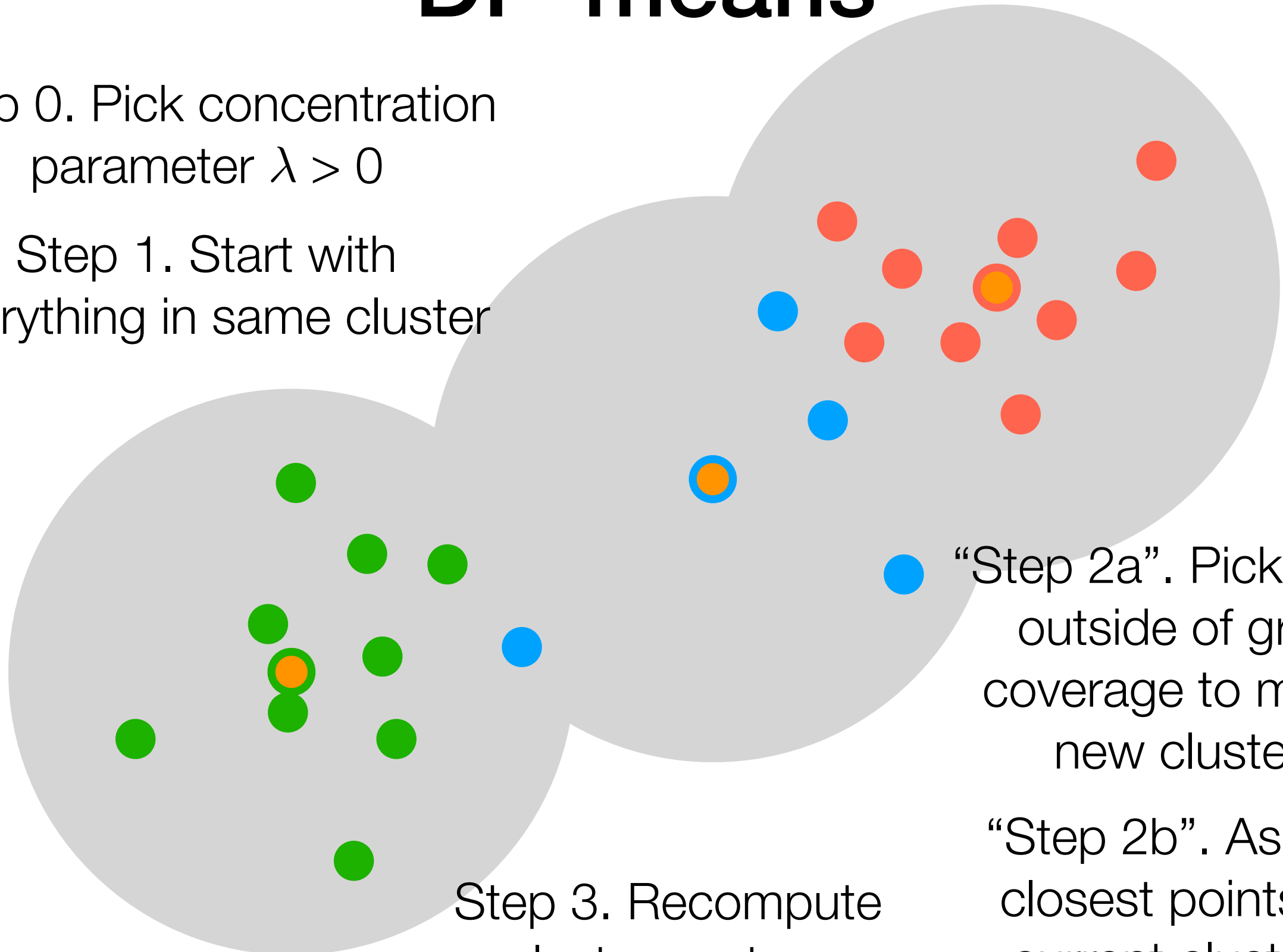
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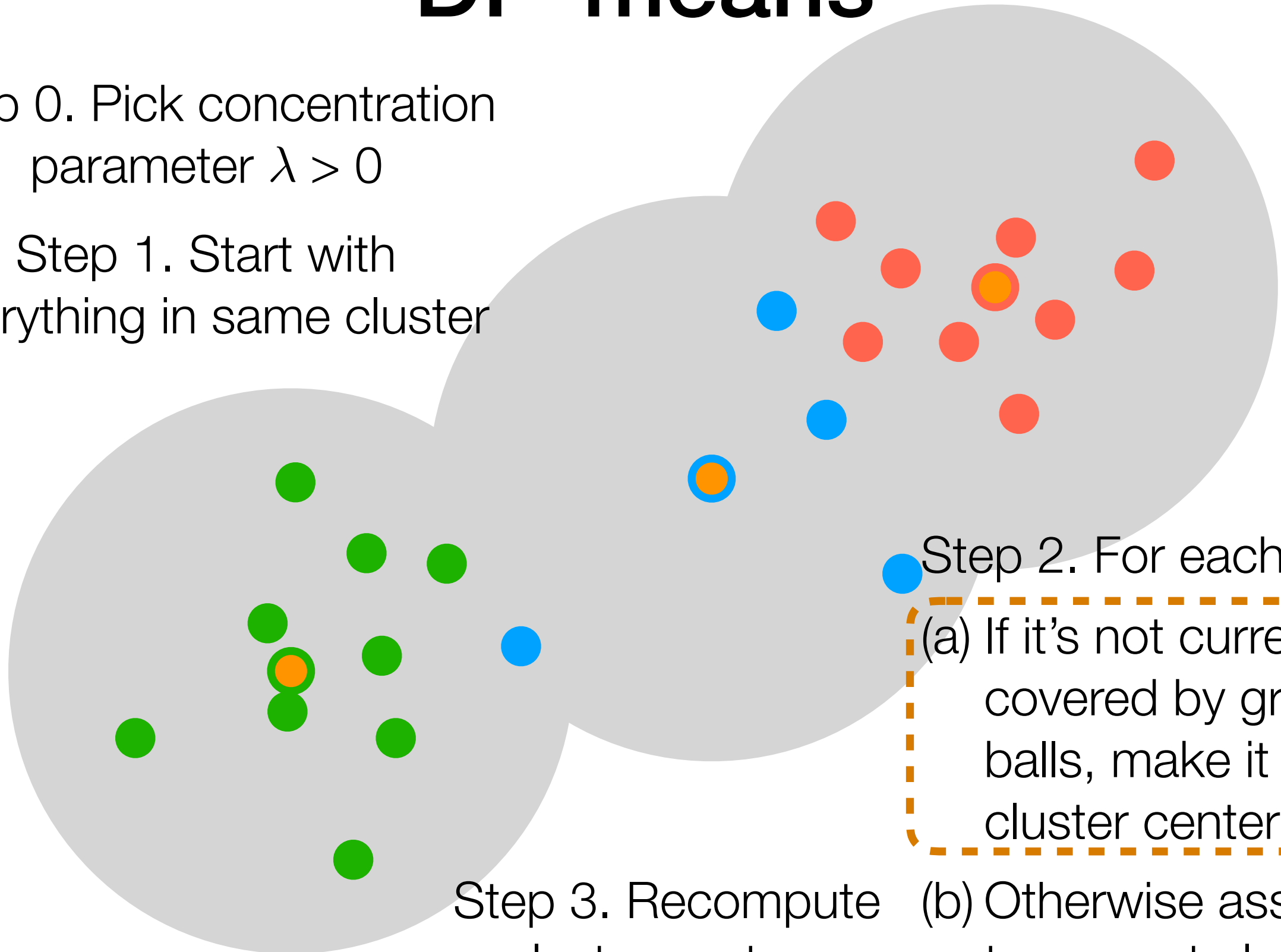
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# DP-means

Step 0. Pick concentration parameter  $\lambda > 0$

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Step 2. For each point:

(a) If it's not currently covered by gray balls, make it a new cluster center

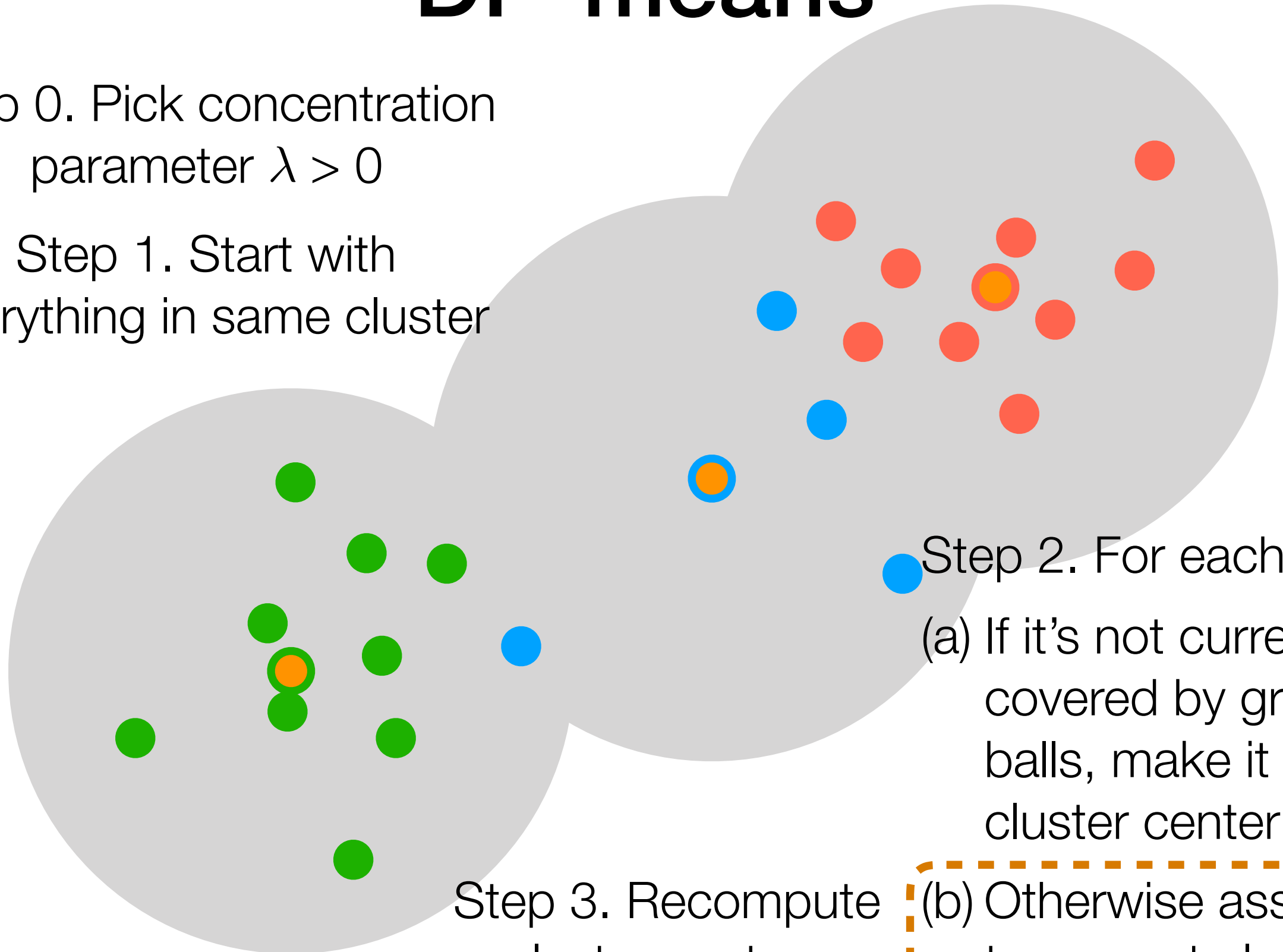
(b) Otherwise assign it to nearest cluster

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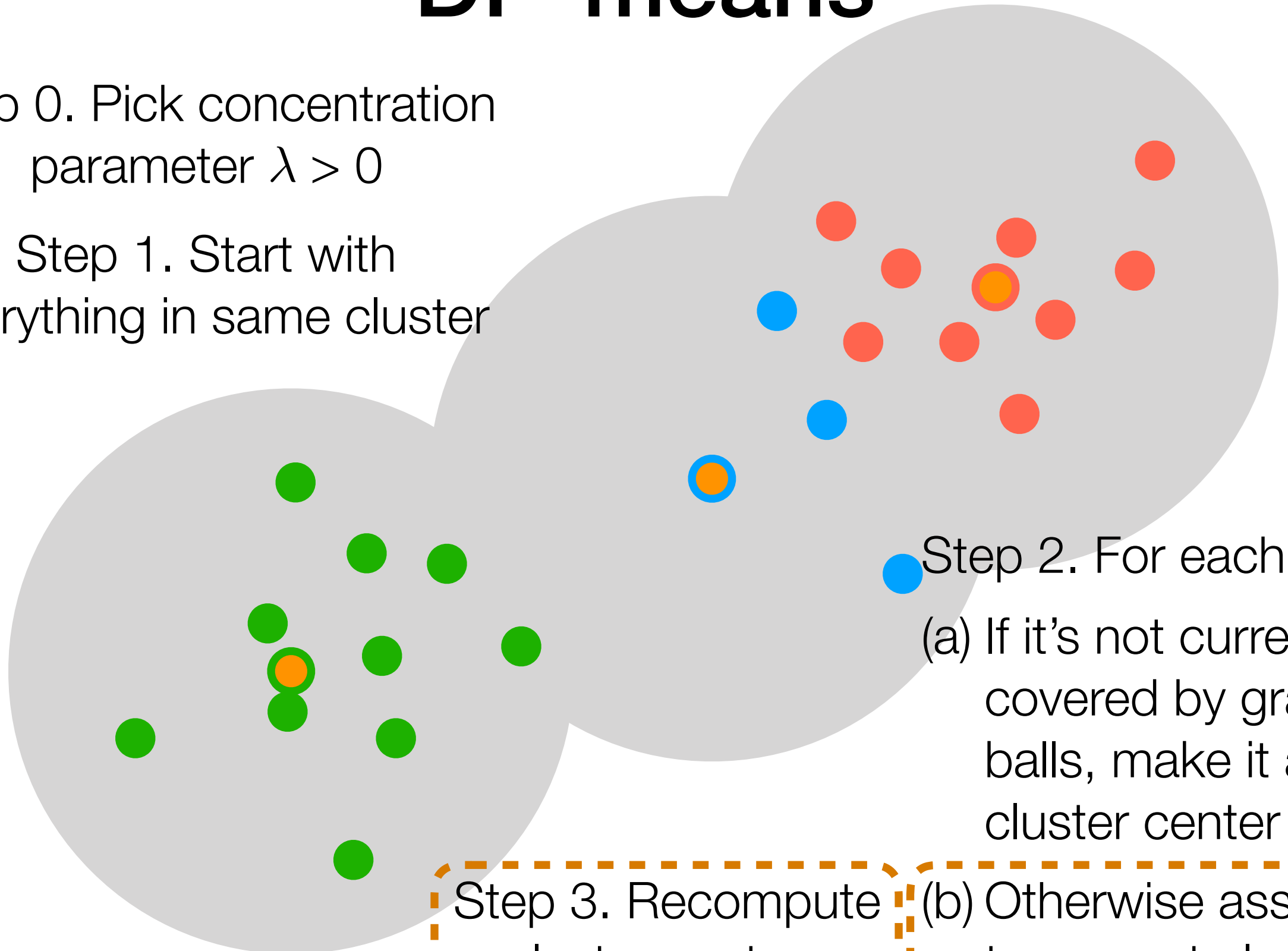
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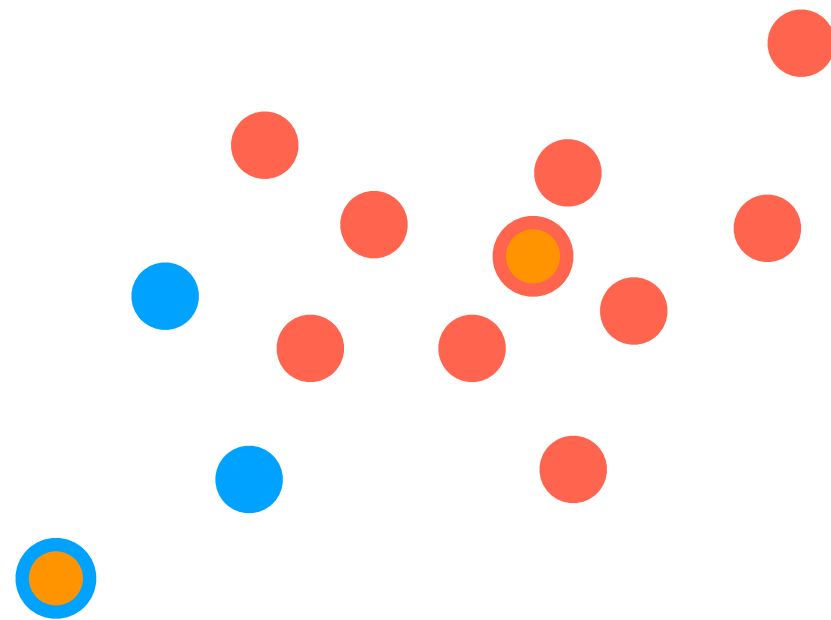
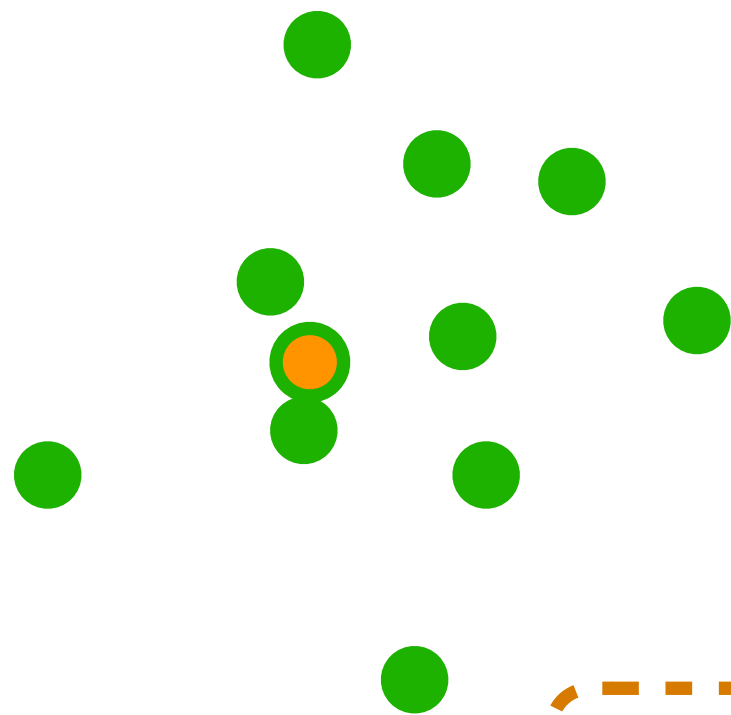
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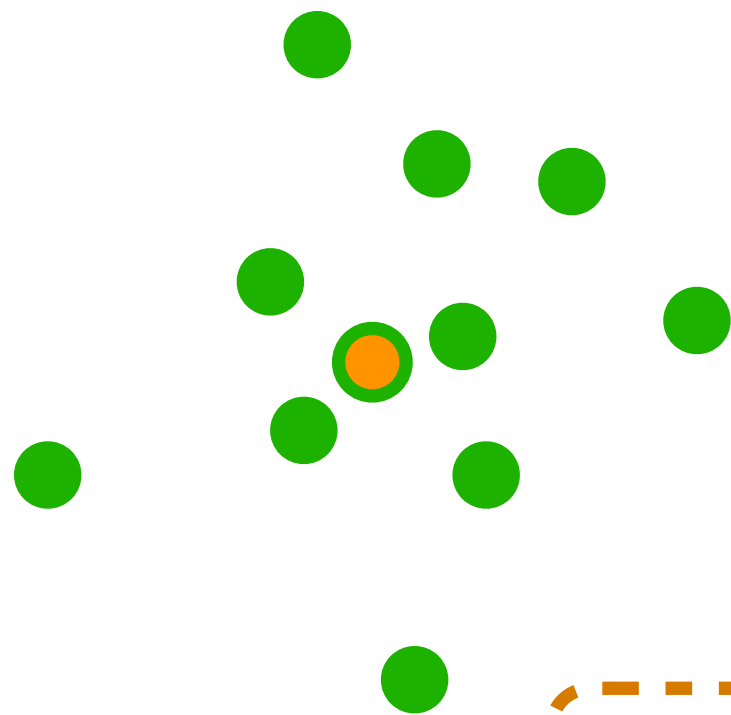
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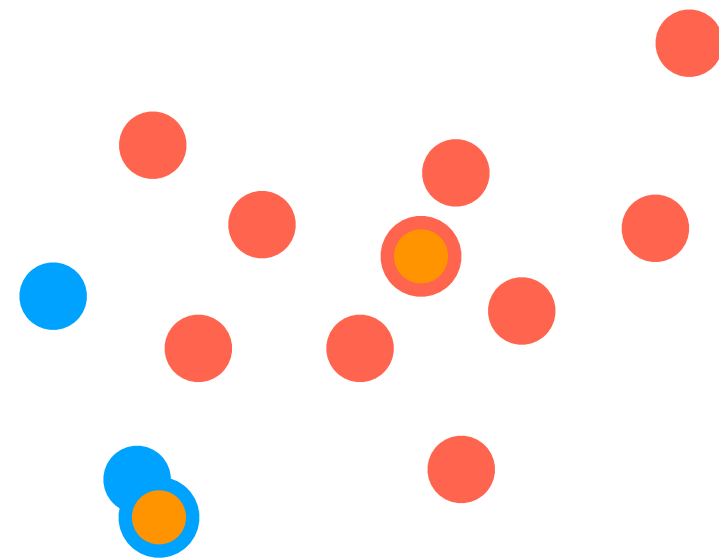
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Step 3. Recompute cluster centers



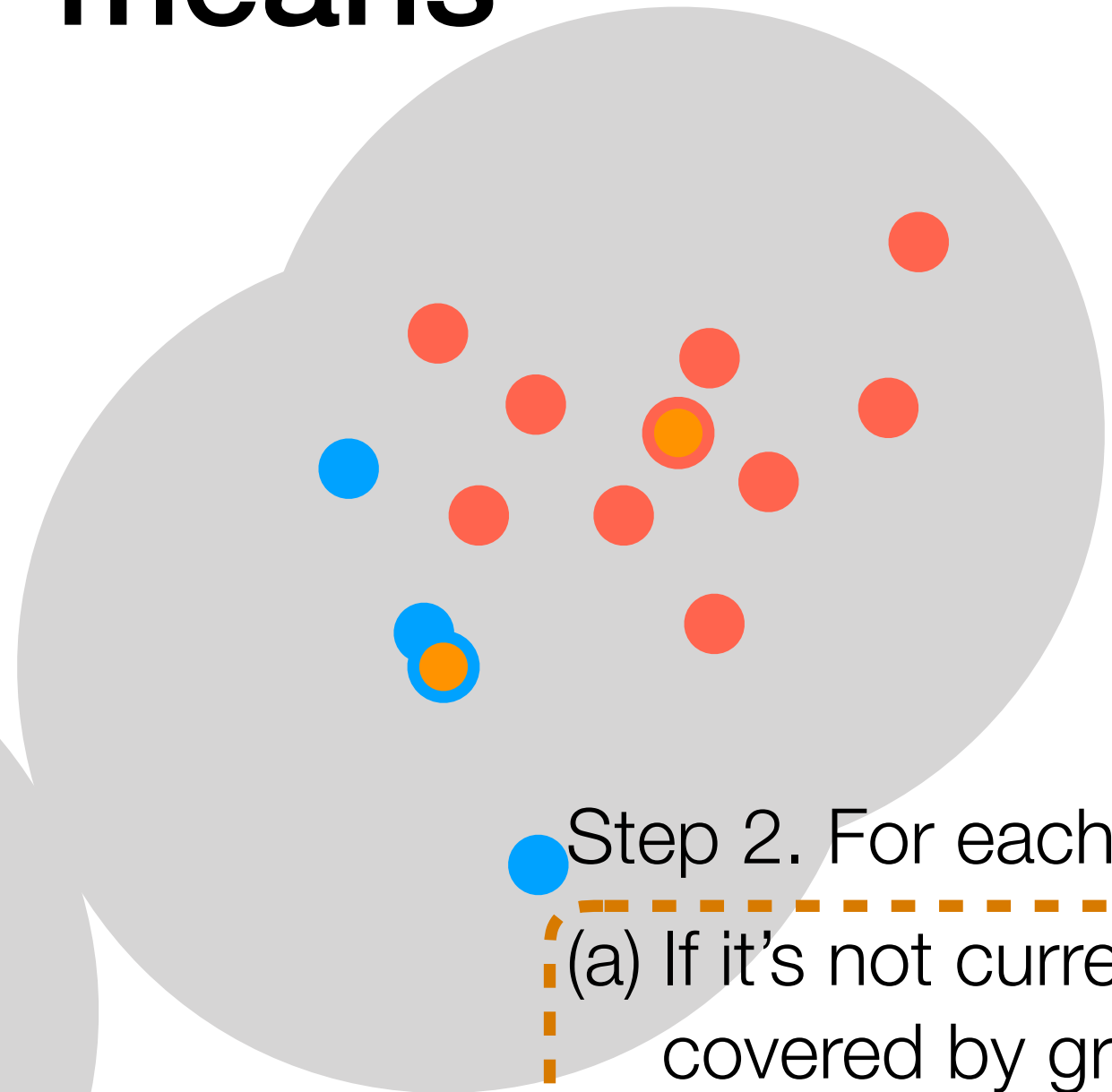
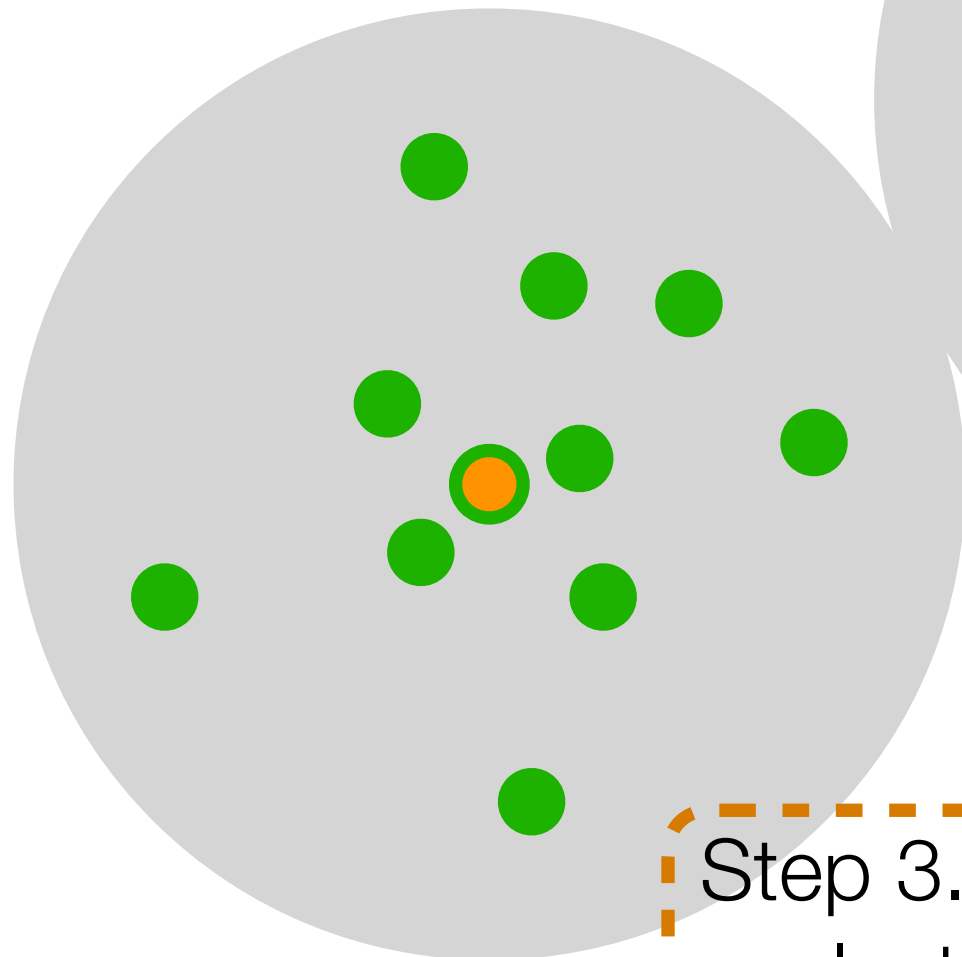
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  - (a) If it's not currently covered by gray balls, make it a new cluster center
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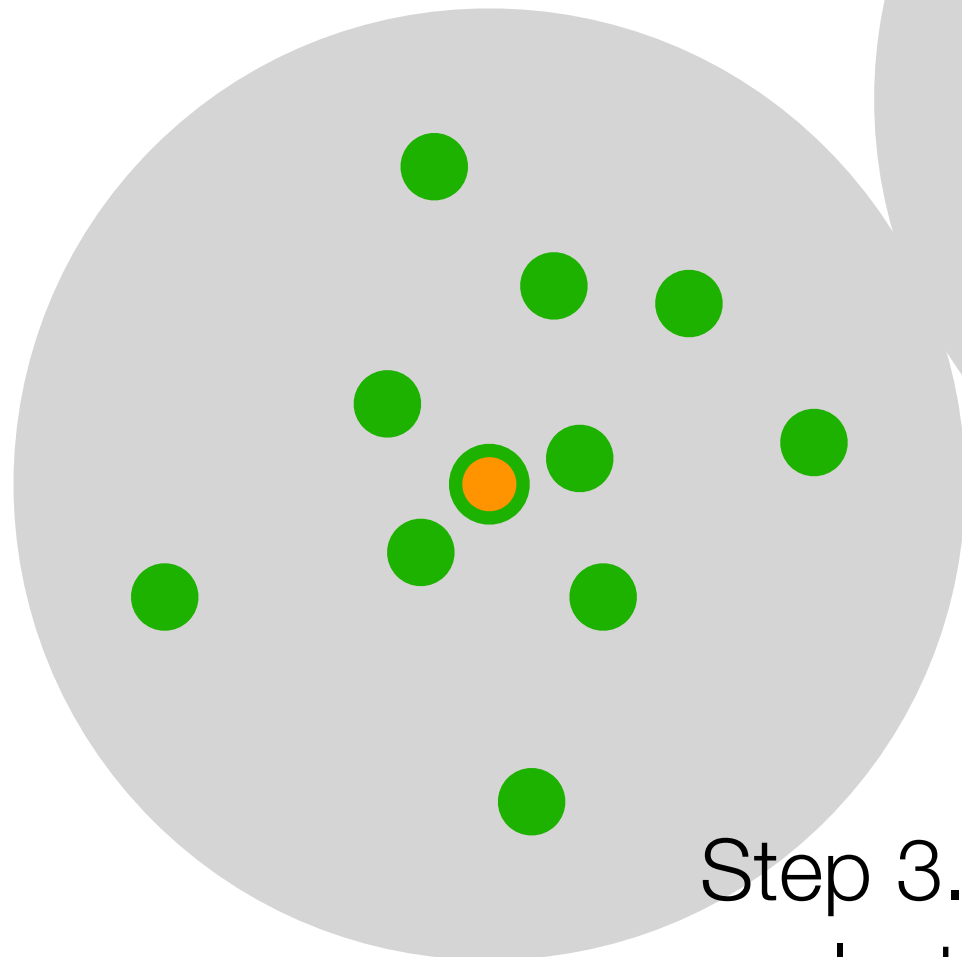
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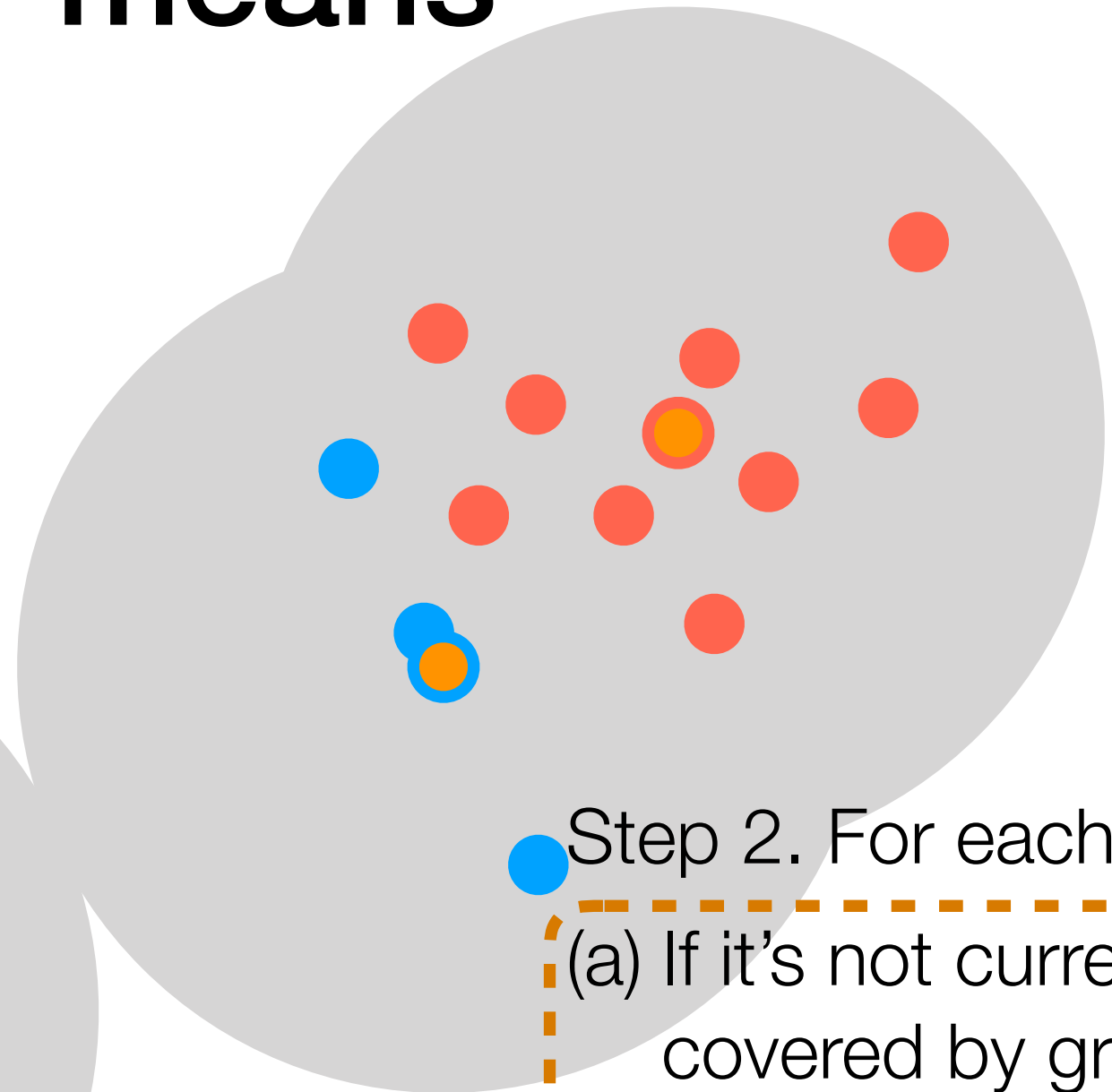
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Step 3. Recompute cluster centers



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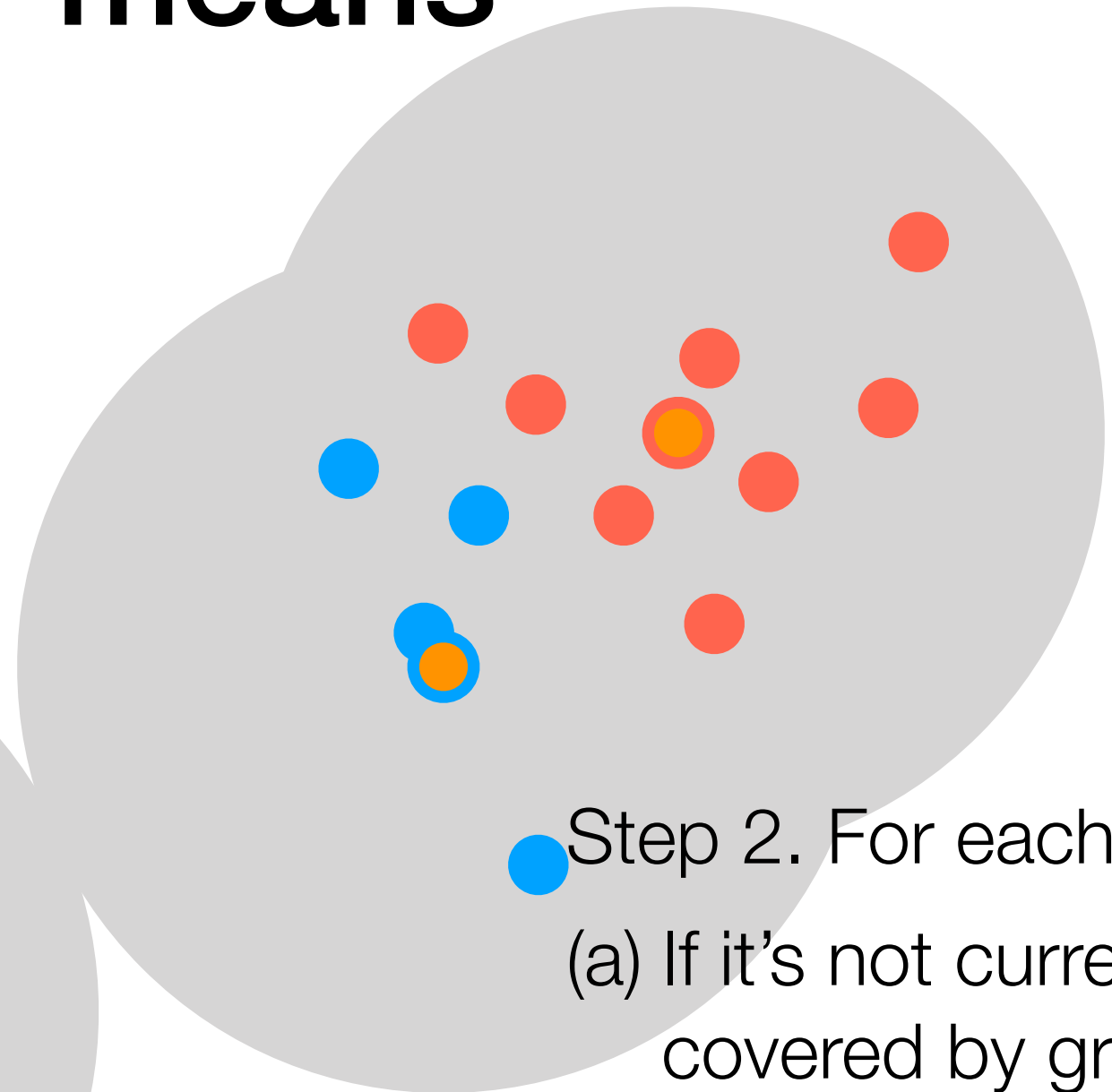
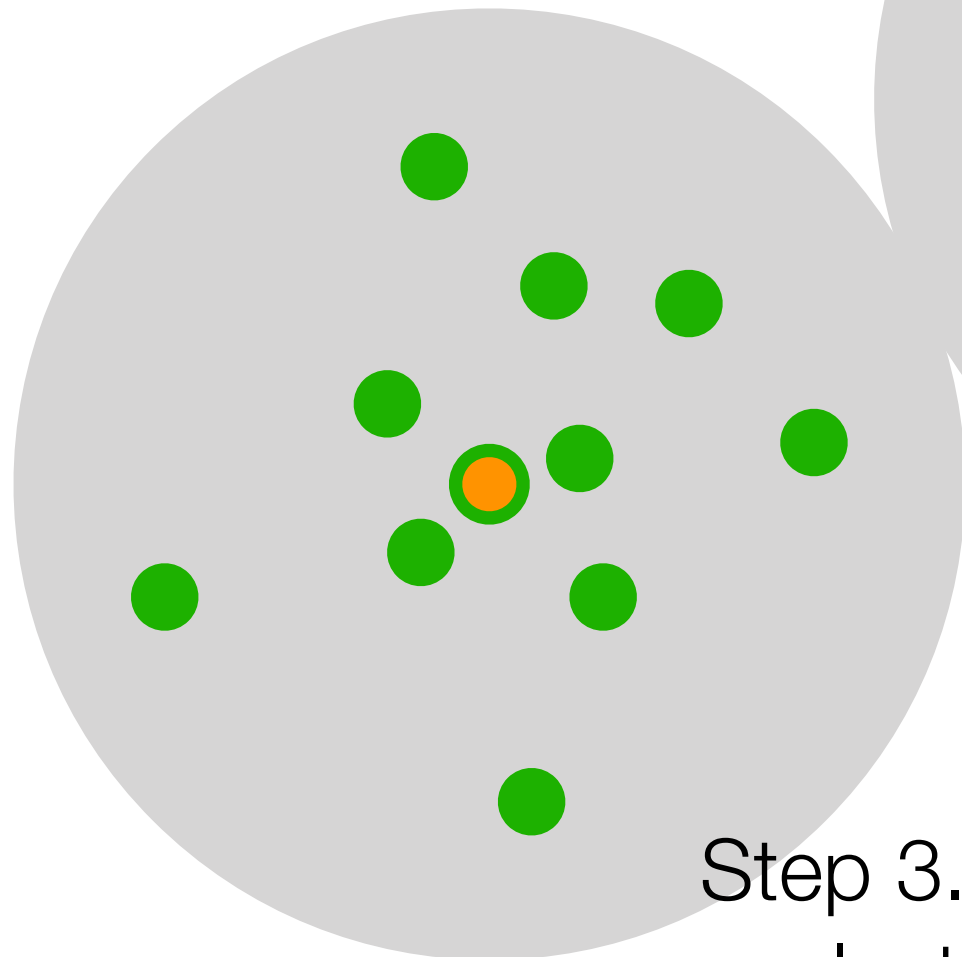
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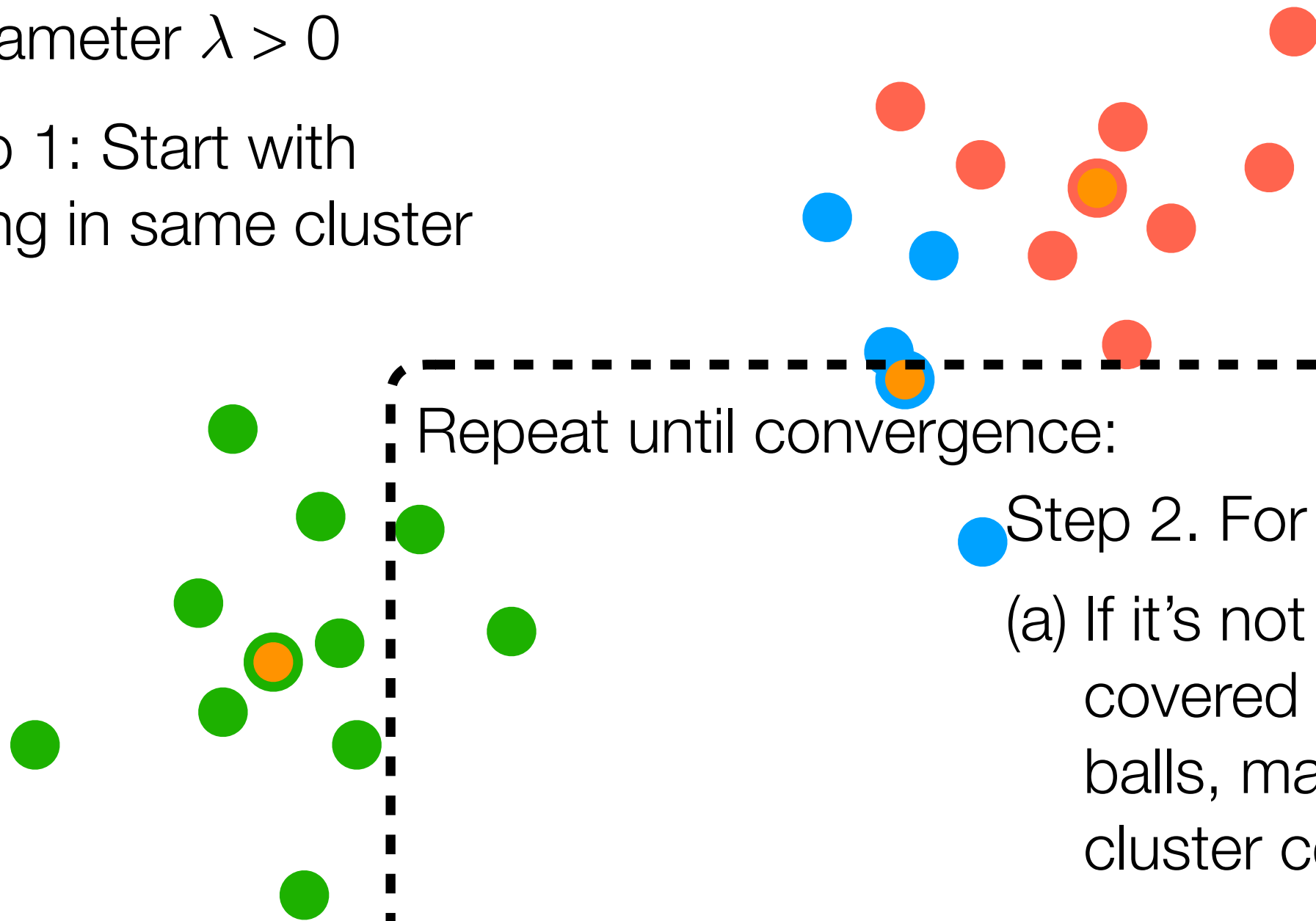
Step 3. Recompute cluster centers

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# DP-means

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Repeat until convergence:

Step 2. For each point:

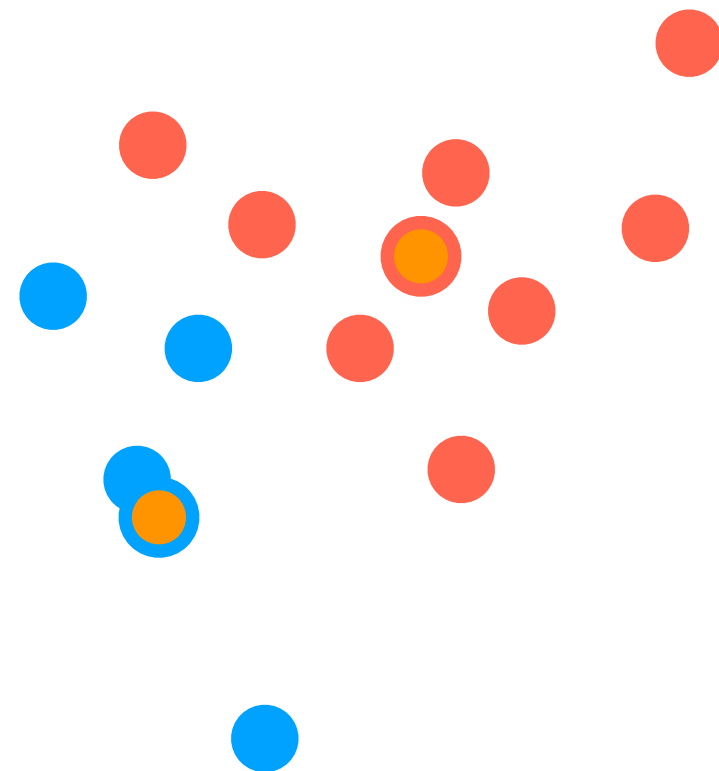
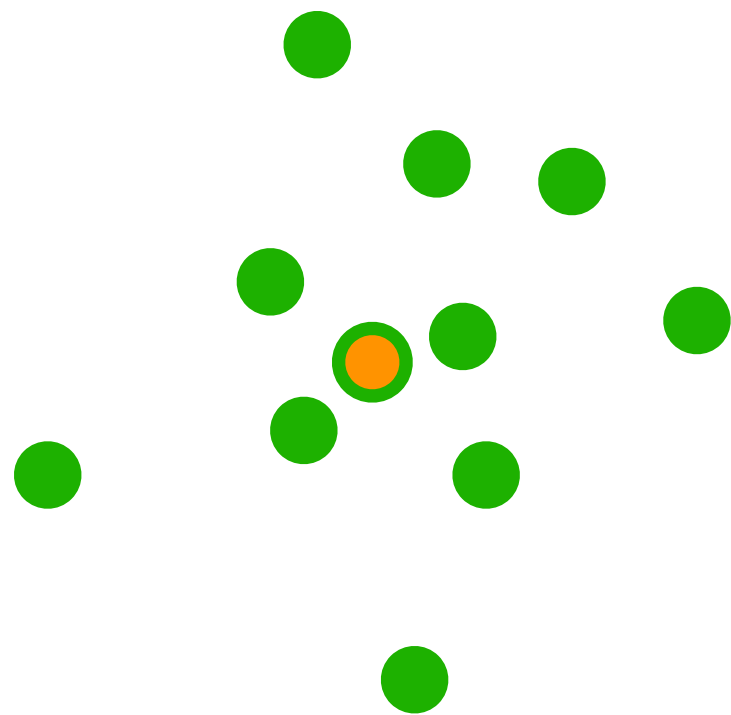
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# DP-means

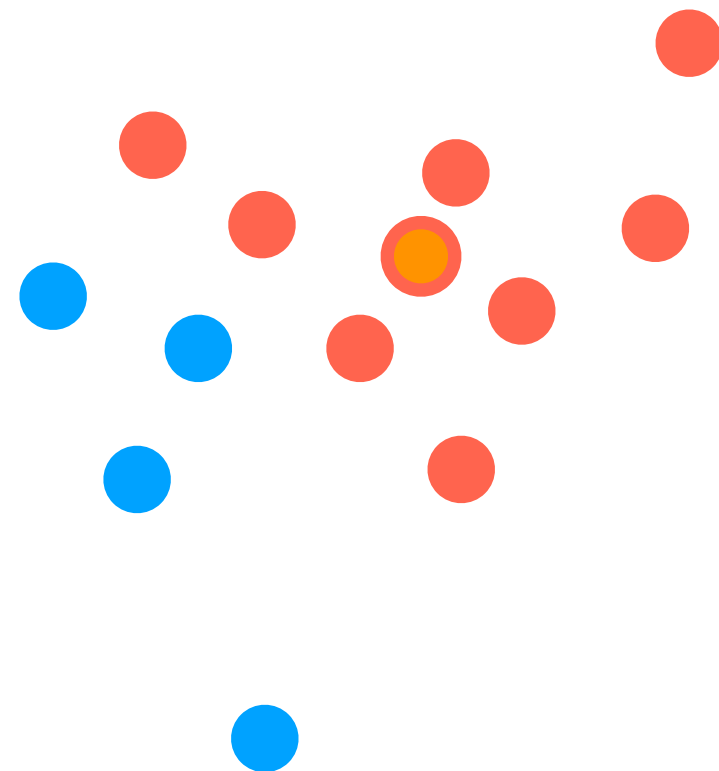
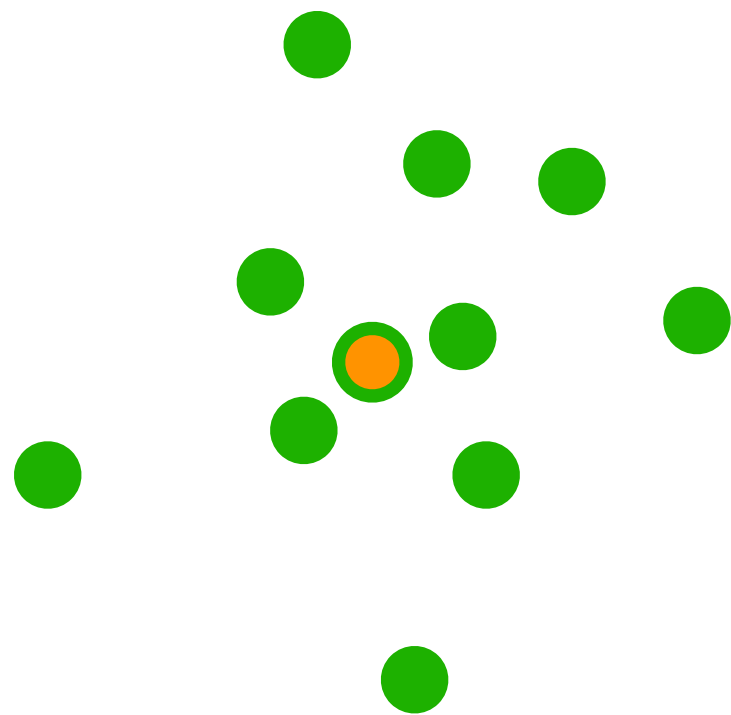
As you saw in the DP-GMM demo  
(and is similar with DP-means),  
DP-means can produce a few  
extra small clusters



In practice: reassign points in small  
clusters to bigger clusters

# DP-means

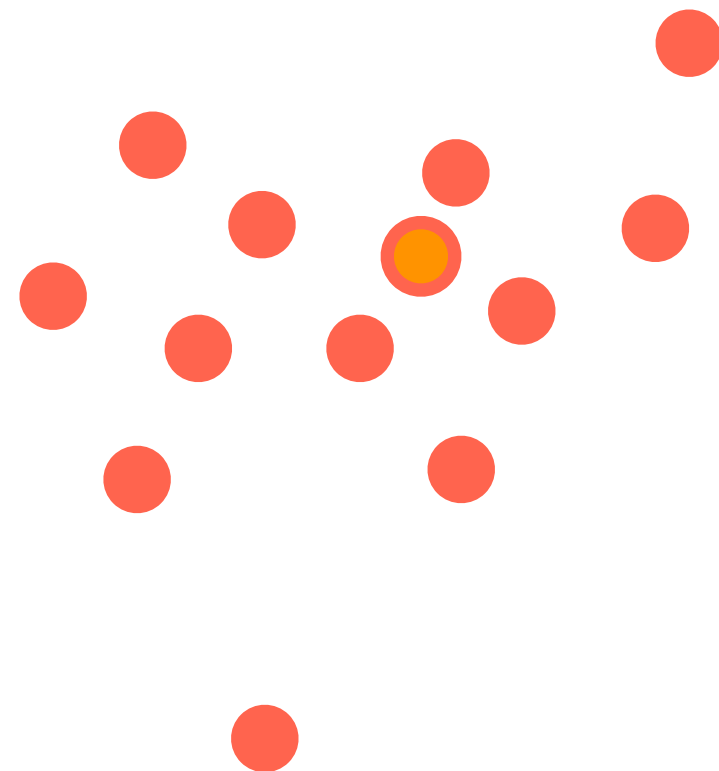
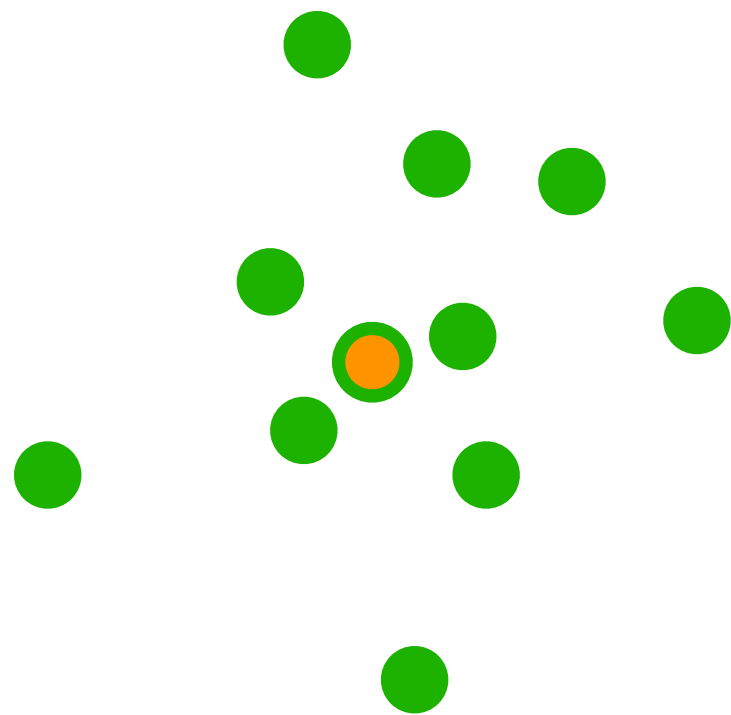
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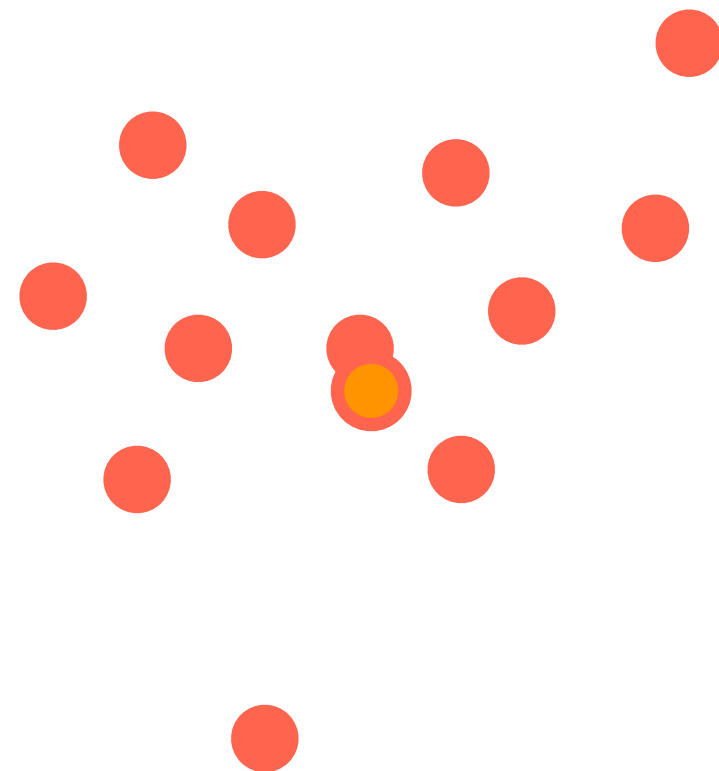
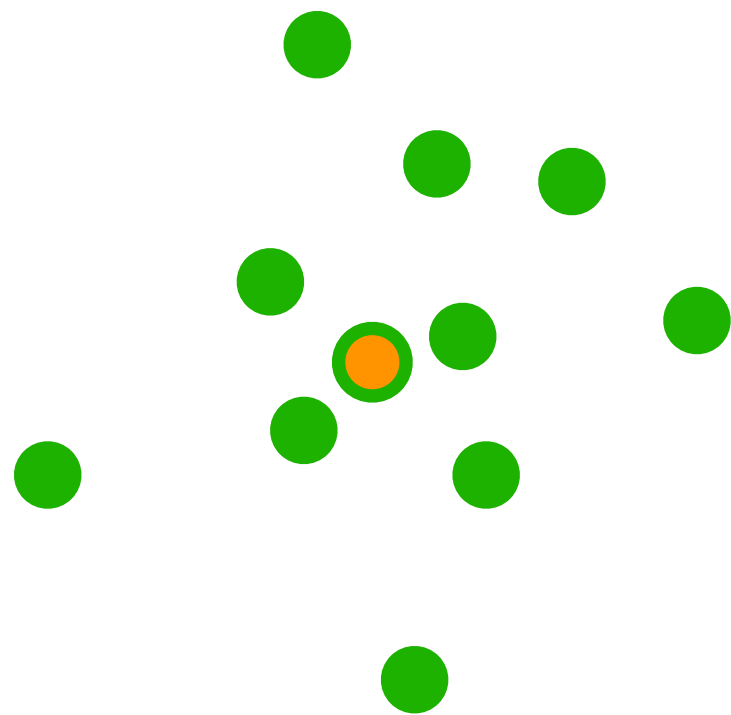


In practice: reassign points in small  
clusters to bigger clusters

Can recompute cluster centers

# DP-means

As you saw in the DP-GMM demo  
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DP-means can produce a few  
extra small clusters



In practice: reassign points in small  
clusters to bigger clusters

Can recompute cluster centers



# Big picture: DP-means & DP-GMM have a “concentration” parameter roughly controlling *size* of clusters rather than *number* of clusters

If your problem can more naturally be thought of as having cluster sizes that should not be too large, can use DP-means/DP-GMM instead of k-means/GMM

**Real example.** *Satellite image analysis of rural India to find villages*

Each cluster is a village: don't know how many villages there are total but rough upper bound on radius of village can be specified

→ DP-means provides a decent solution!

# Other Ways for Choosing $k$

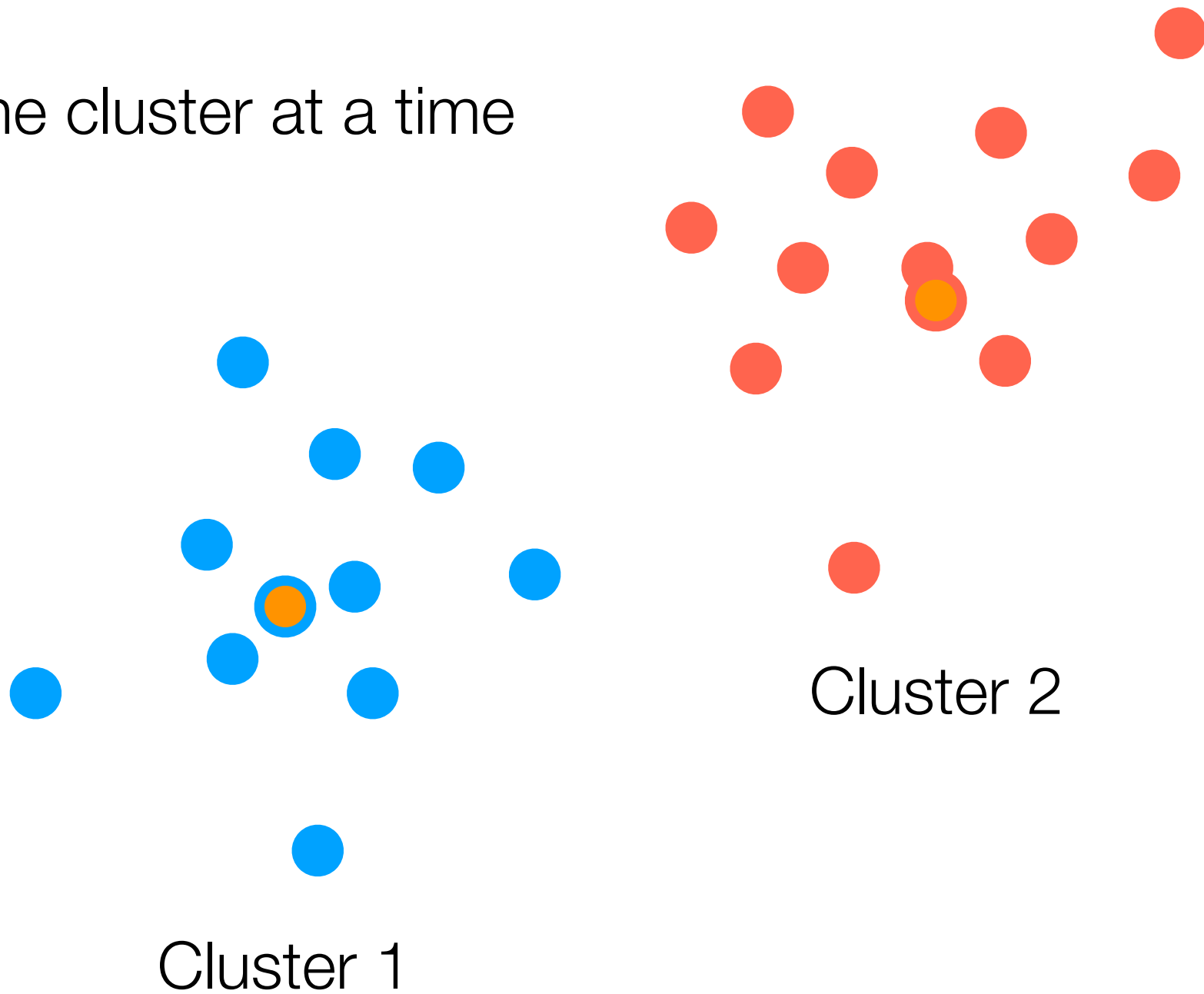
- Choose a cost function to compute for different  $k$ 
  - In general, not easy! Need some intuition for what “good” clusters are
  - Ideally: cost function should relate to your application of interest
- Pick  $k$  achieving lowest cost

**Here's an example of a cost  
function you don't want to use**

But hey it's worth a shot

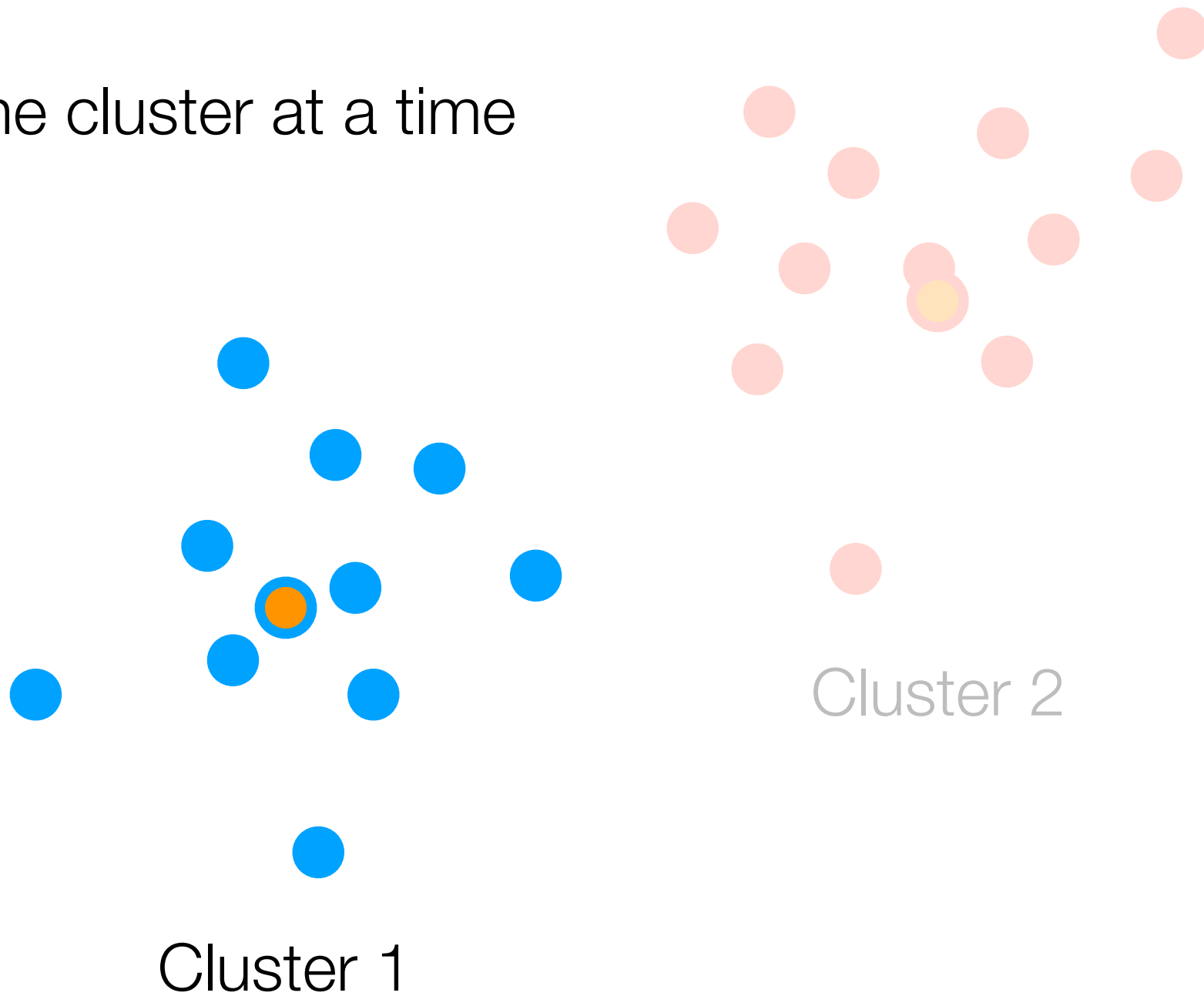
# Residual Sum of Squares

Look at one cluster at a time



# Residual Sum of Squares

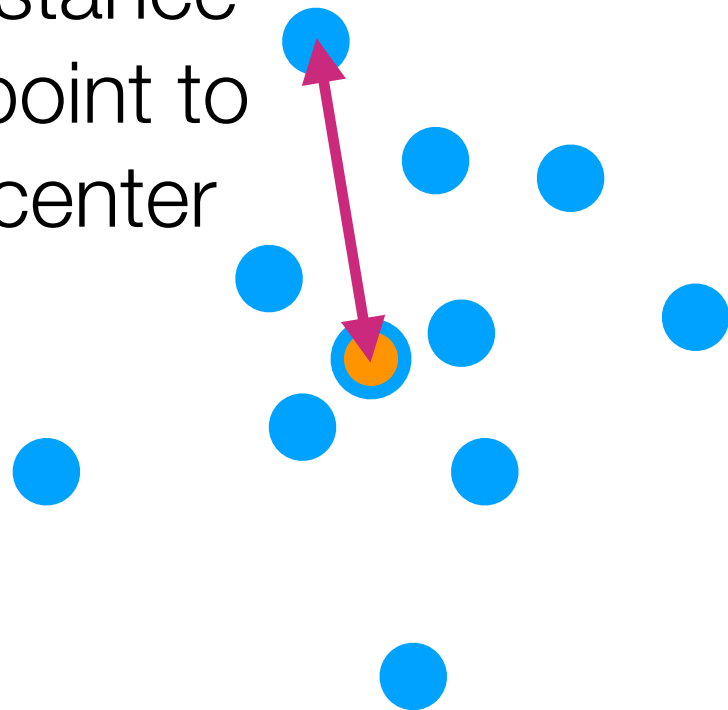
Look at one cluster at a time



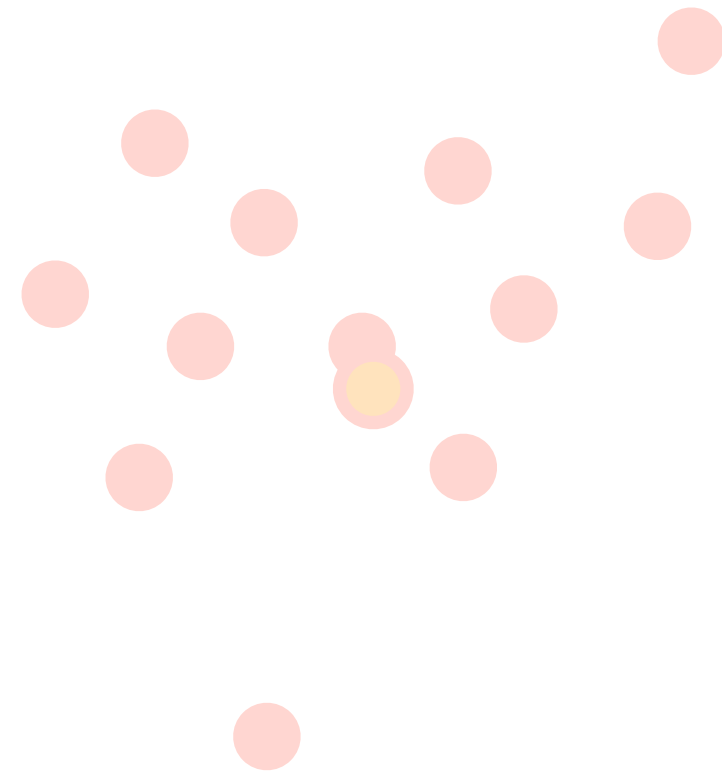
# Residual Sum of Squares

Look at one cluster at a time

Measure distance  
from each point to  
its cluster center



Cluster 1

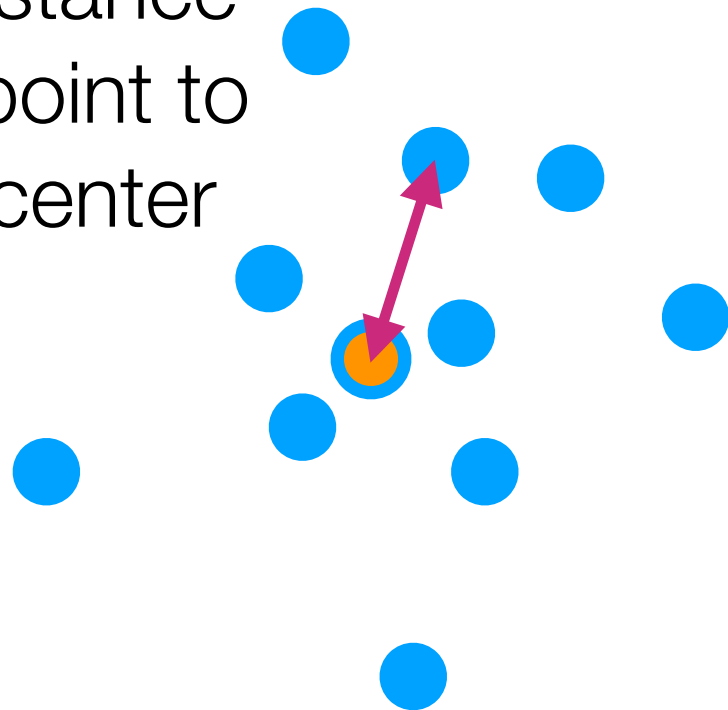


Cluster 2

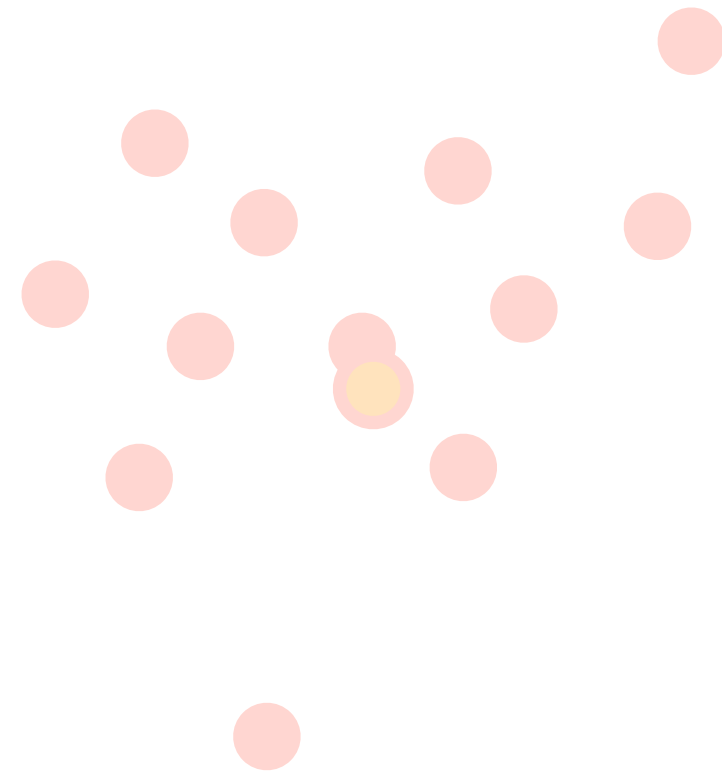
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Cluster 1

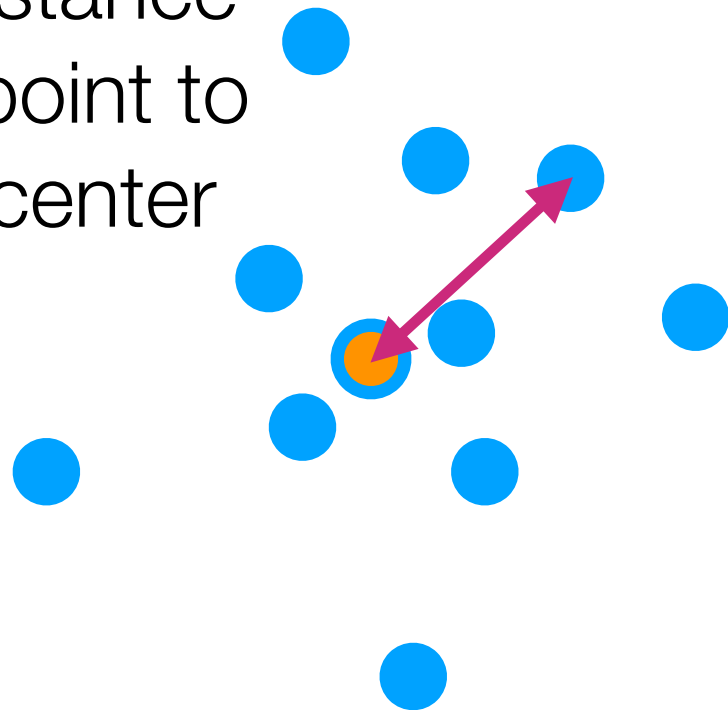


Cluster 2

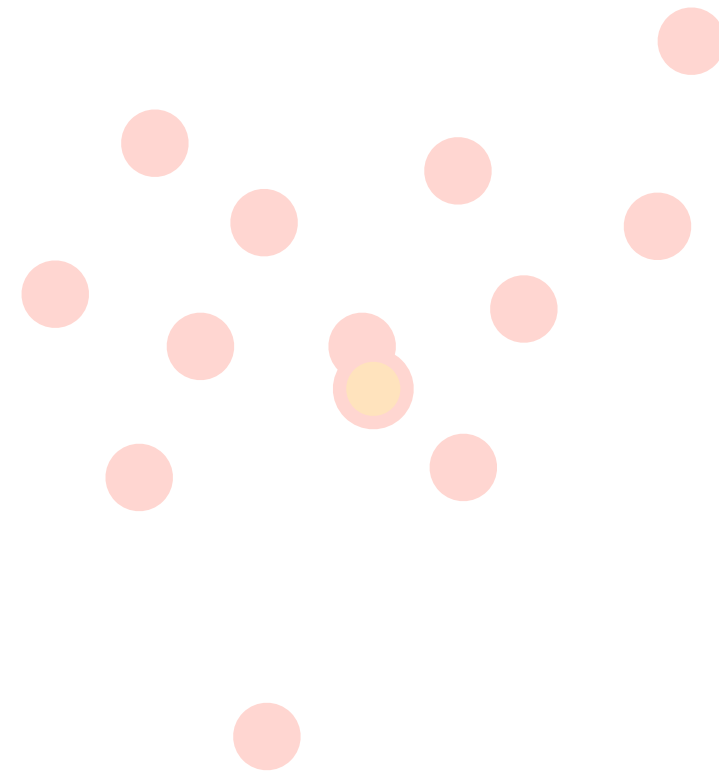
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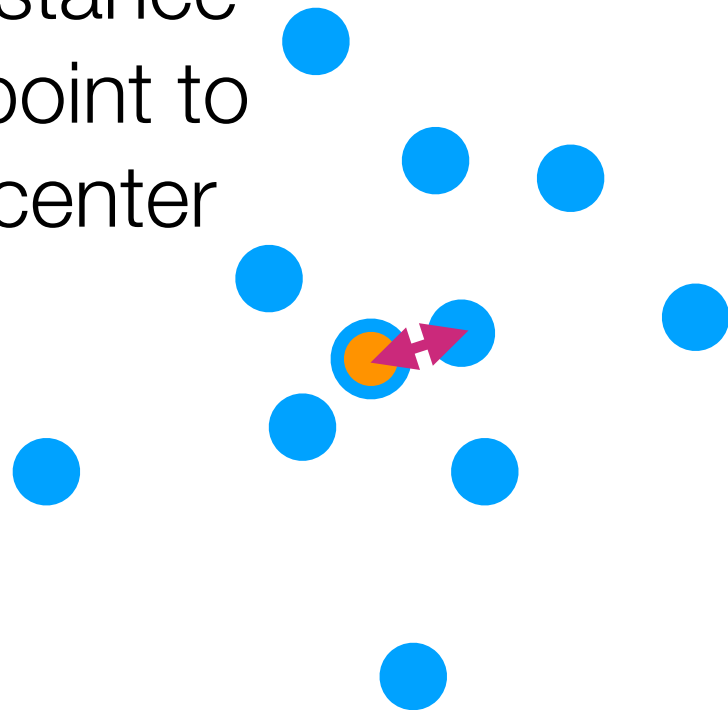
Cluster 2



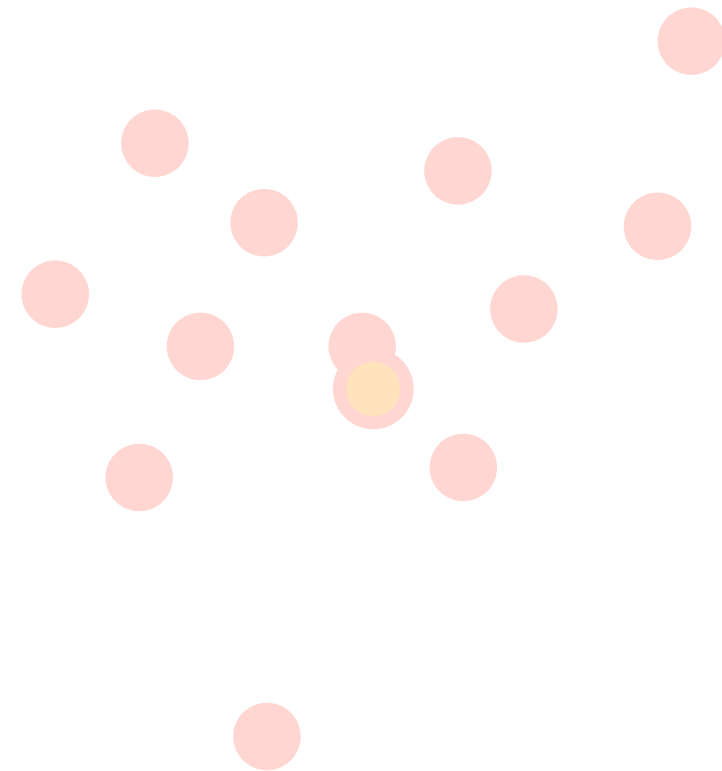
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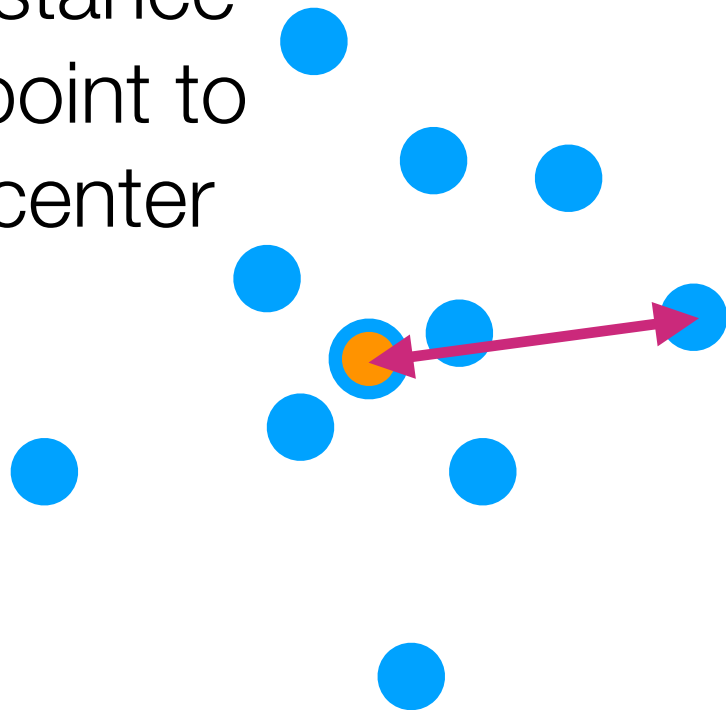


Cluster 2

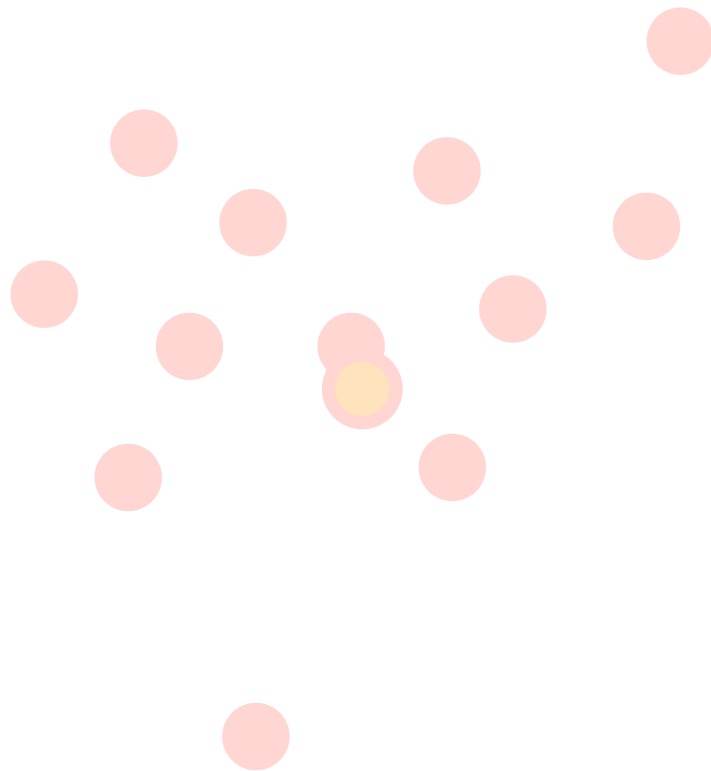
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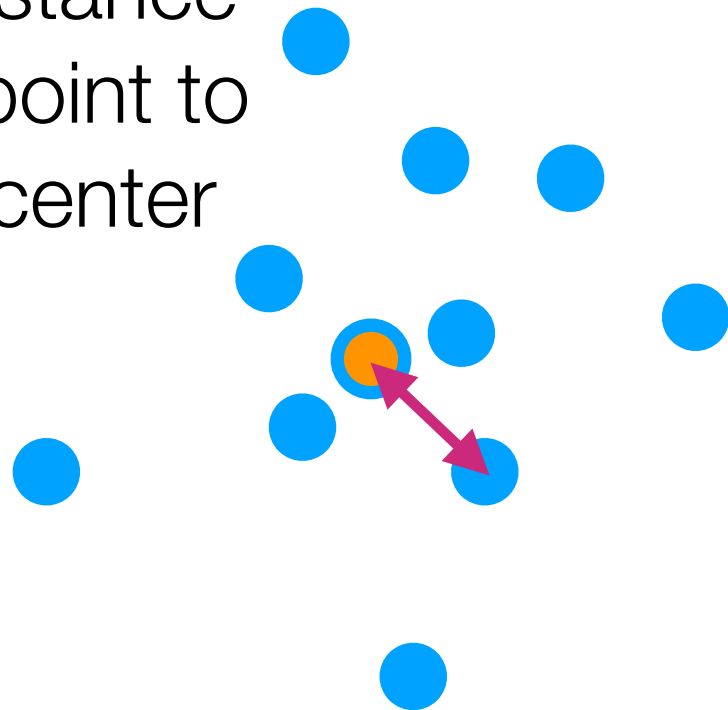


Cluster 2

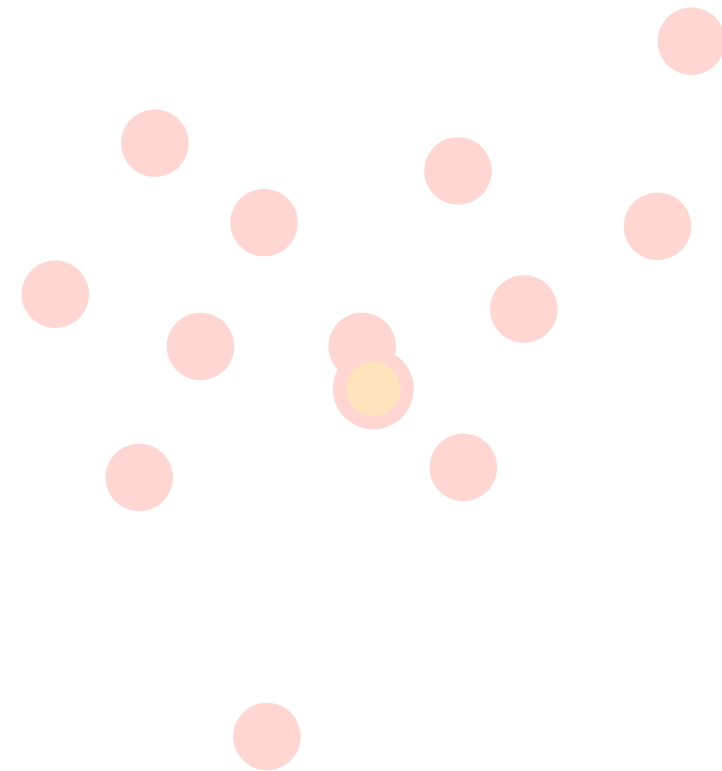
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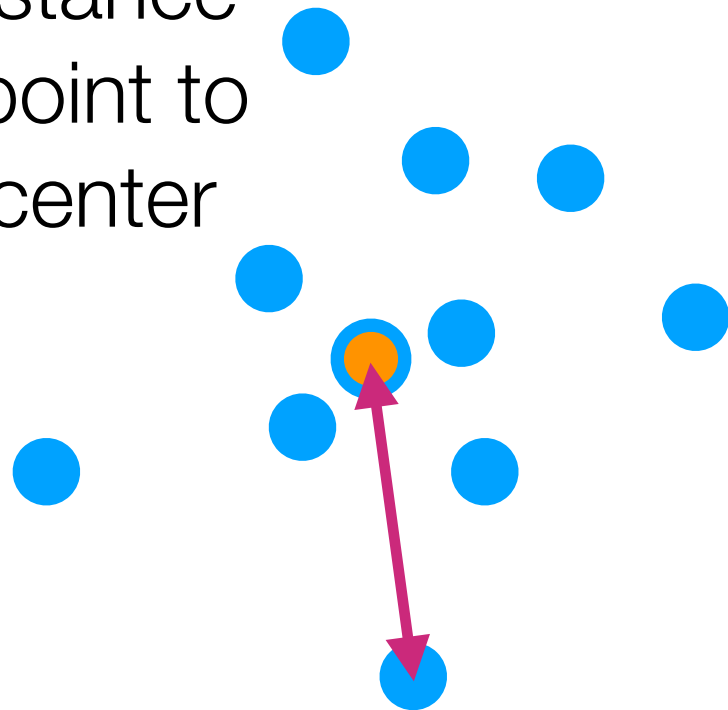


Cluster 2

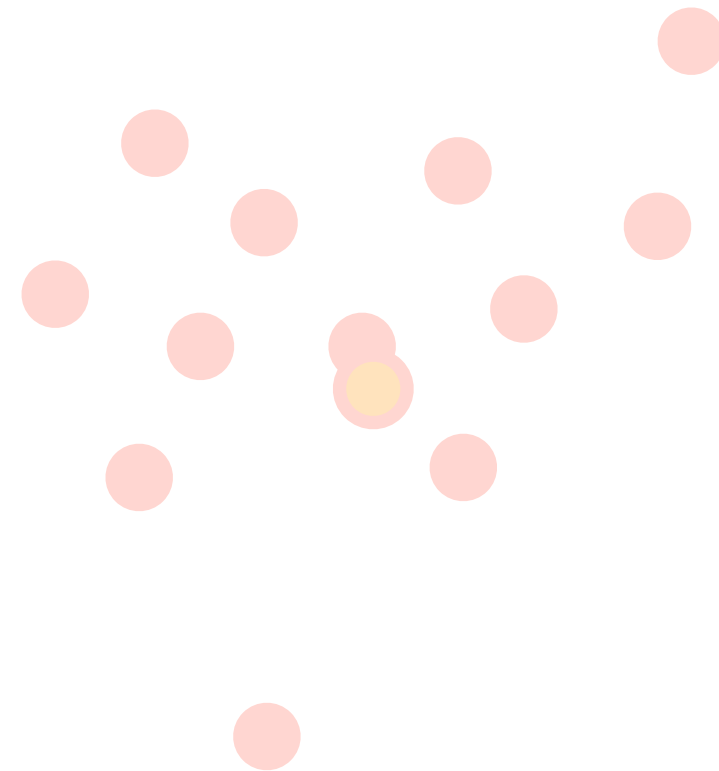
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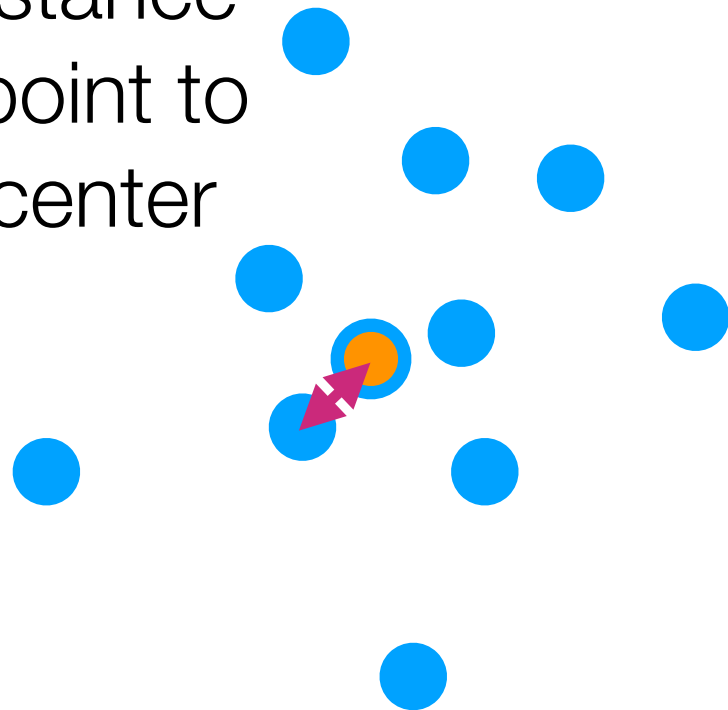


Cluster 2

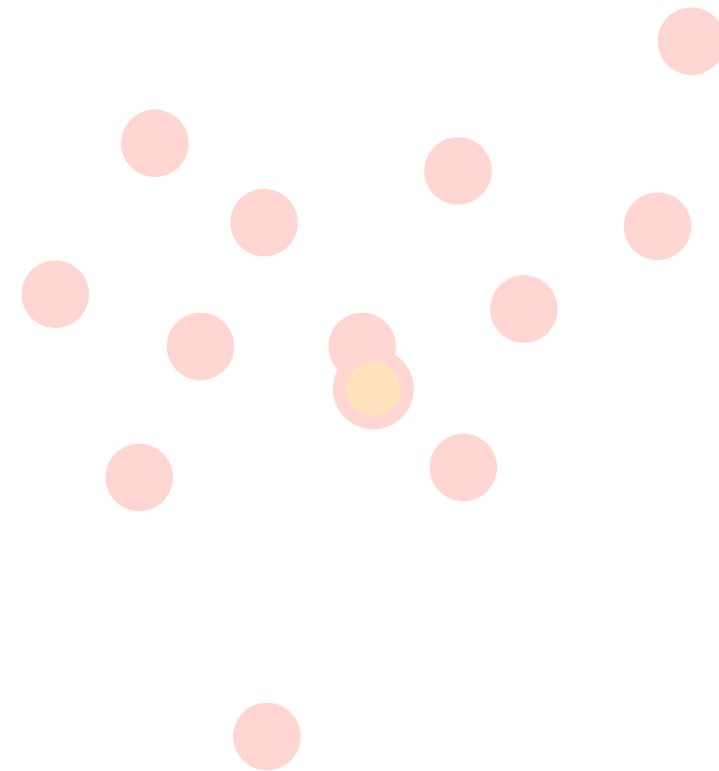
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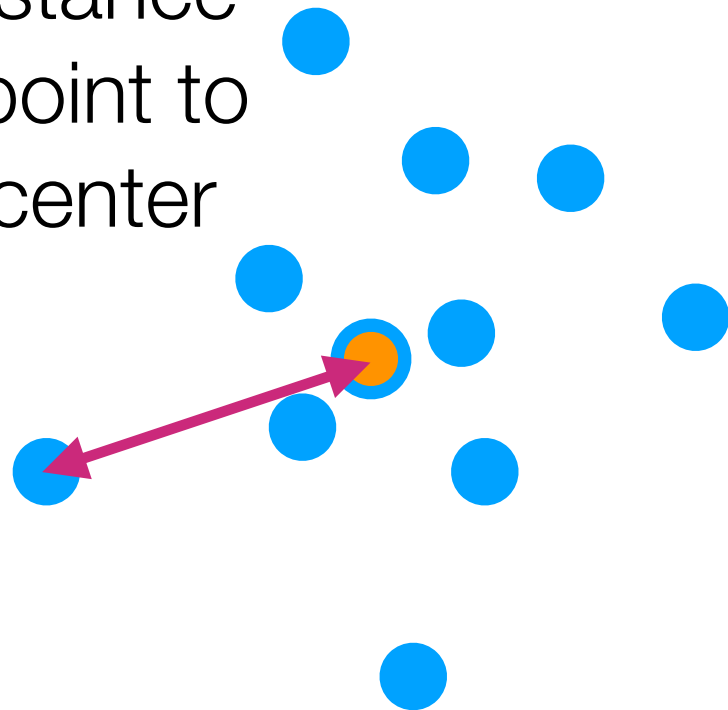


Cluster 2

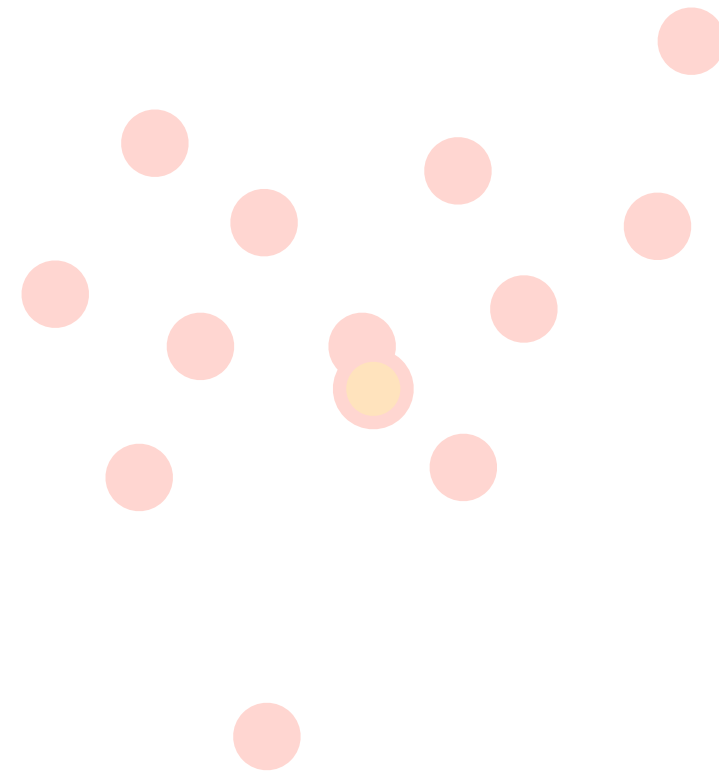
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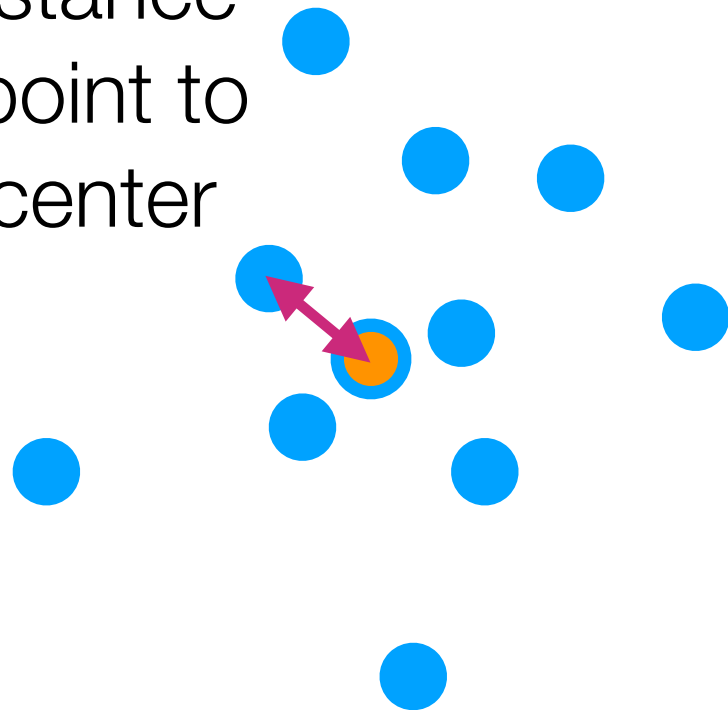


Cluster 2

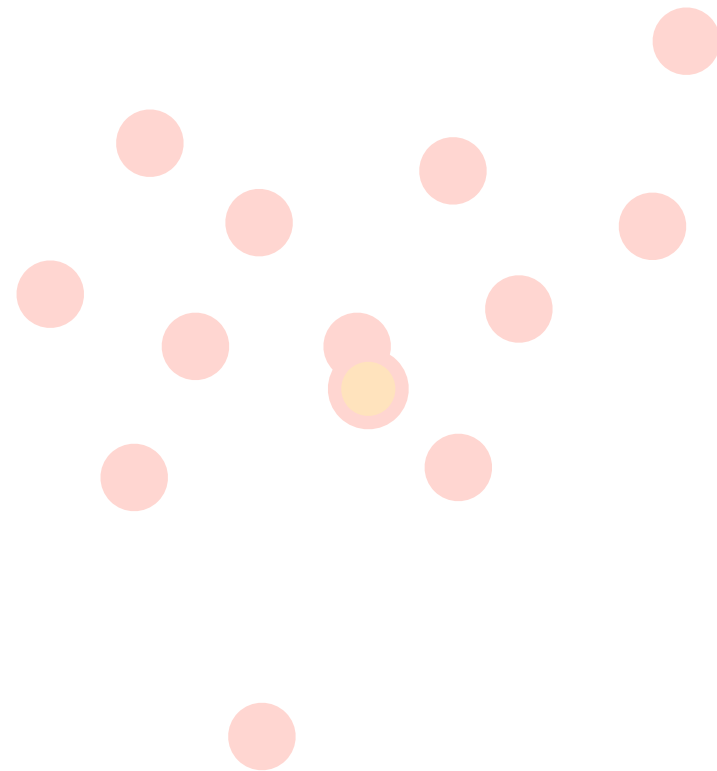
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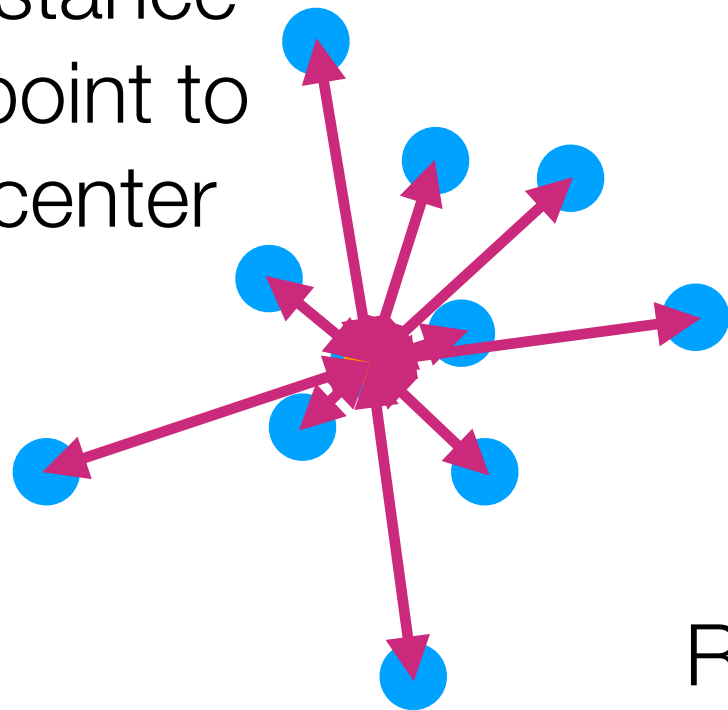


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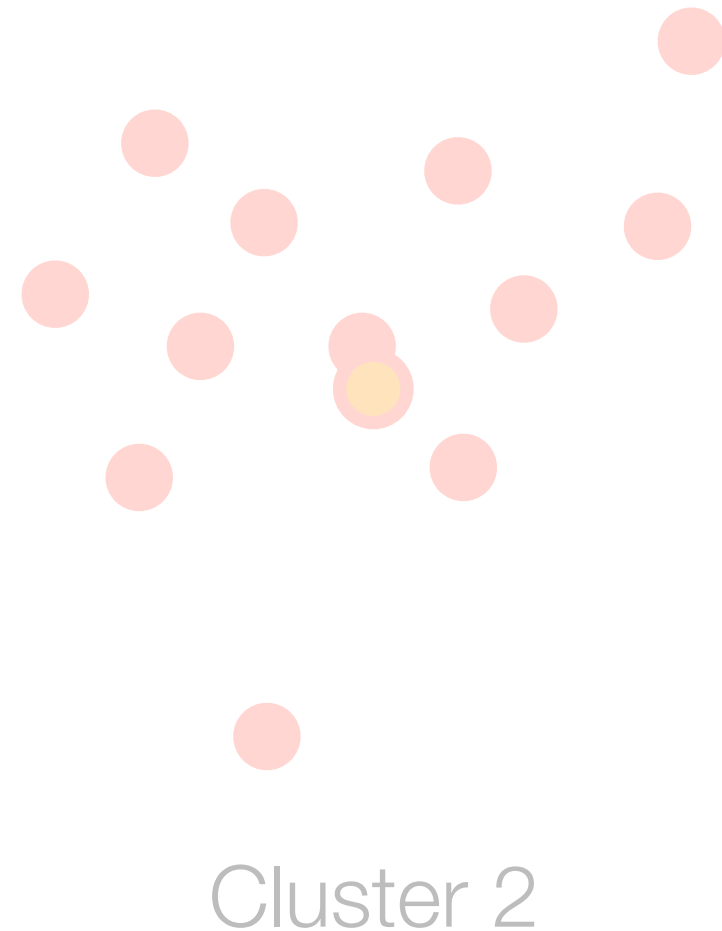
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Measure distance from each point to its cluster center



Cluster 1



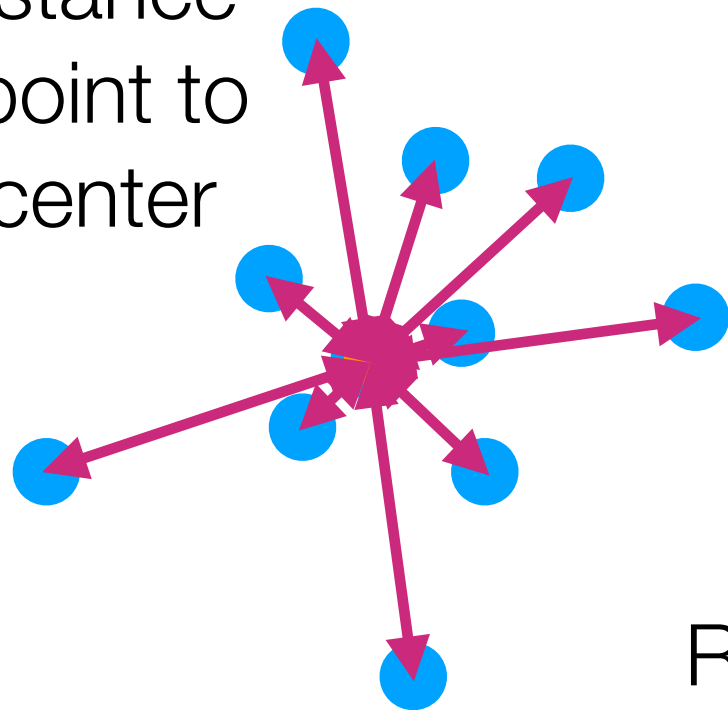
Residual sum of squares for cluster 1:  
sum of *squared* purple lengths



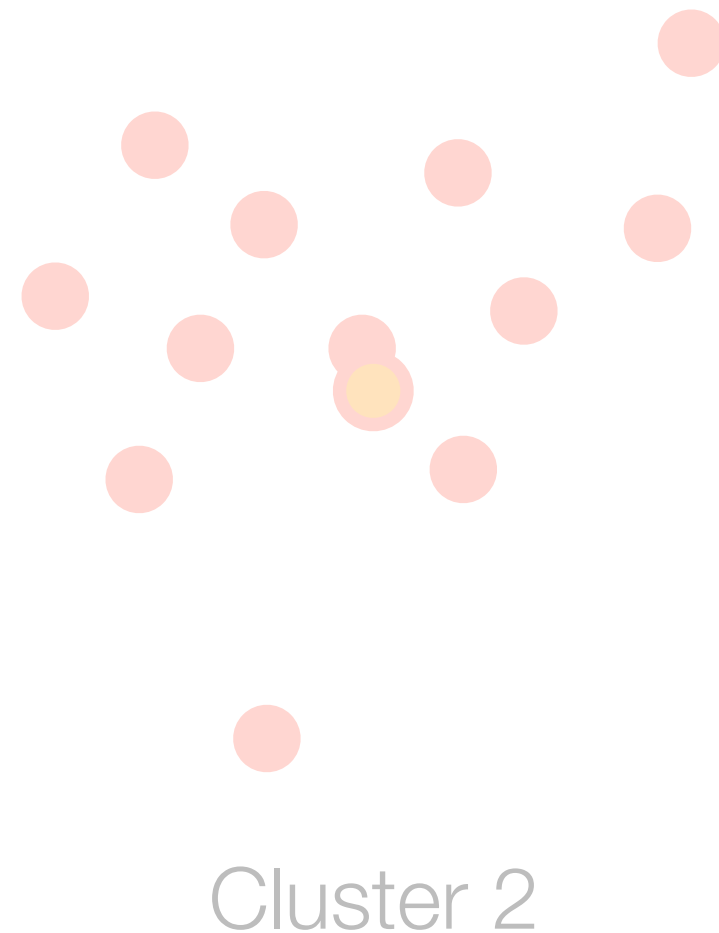
# Residual Sum of Squares

Look at one cluster at a time

Measure distance from each point to its cluster center



Cluster 1



Residual sum of squares for cluster 1:

$$RSS_1 = \sum_{x \in \text{cluster 1}} \|x - \mu_1\|^2$$

# Residual Sum of Squares

Look at one cluster at a time

Measure distance from each point to its cluster center



Cluster 1



Cluster 2

Repeat similar calculation for other cluster

Residual sum of squares for cluster 2:

$$RSS_2 = \sum_{x \in \text{cluster 2}} \|x - \mu_2\|^2$$

# Residual Sum of Squares

$$\text{RSS} = \text{RSS}_1 + \text{RSS}_2 = \sum_{x \in \text{cluster 1}} \|x - \mu_1\|^2 + \sum_{x \in \text{cluster 2}} \|x - \mu_2\|^2$$

Measure distance  
from each point to  
its cluster center

In general if there are  $k$  clusters:

$$\text{RSS} = \sum_{g=1}^k \text{RSS}_g = \sum_{g=1}^k \sum_{x \in \text{cluster } g} \|x - \mu_g\|^2$$

repeat similar calculation  
for other cluster

Remark:  $k$ -means *tries* to minimize RSS

(it does so *approximately*, with no guarantee of optimality)

Cluster 1

RSS only really makes sense for clusters that look like circles

# Why is RSS not a good way to choose $k$ ?

What is RSS when  $k$  is equal to the number of data points?

# A Good Way to Choose $k$

RSS measures *within-cluster variation*

$$W = \text{RSS} = \sum_{g=1}^k \text{RSS}_g = \sum_{g=1}^k \sum_{x \in \text{cluster } g} \|x - \mu_g\|^2$$

Want to also measure *between-cluster variation*

$$B = \sum_{g=1}^k (\# \text{ points in cluster } g) \|\mu_g - \mu\|^2$$

Called the **CH index**

mean of *all* points

[Calinski and Harabasz 1974]

A good score function to use for choosing  $k$ :

$$\text{CH}(k) = \frac{B \cdot (n - k)}{W \cdot (k - 1)}$$

$n$  = total # points

Pick  $k$  with highest  $\text{CH}(k)$

(Choose  $k$  among 2, 3, ... up to pre-specified max)

Another good way is called the **gap statistic** [Tibshirani et al 2001]

# Hierarchical Clustering

# Going from Similarities to Clusters

There's a whole zoo of clustering methods

Two main categories we'll talk about:

## Generative models

1. Pretend data generated by specific model with parameters
2. Learn the parameters ("fit model to data")
3. Use fitted model to determine cluster assignments

## Hierarchical clustering

Top-down: Start with everything in 1 cluster and decide on how to recursively split

Bottom-up: Start with everything in its own cluster and decide on how to iteratively merge clusters

# Divisive Clustering

0. Start with everything  
in the same cluster

1. Use a method to  
split the cluster

(e.g., *k*-means, with  $k = 2$ )



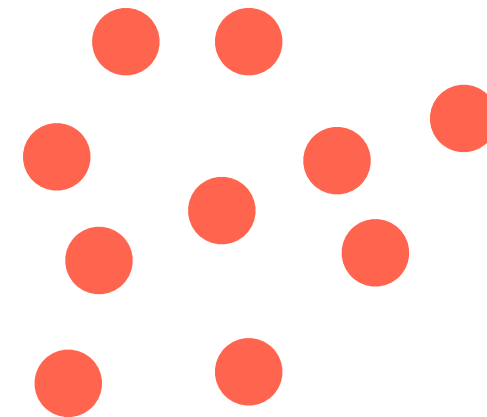
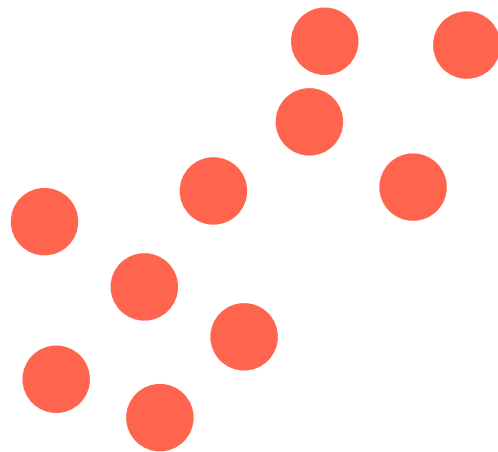
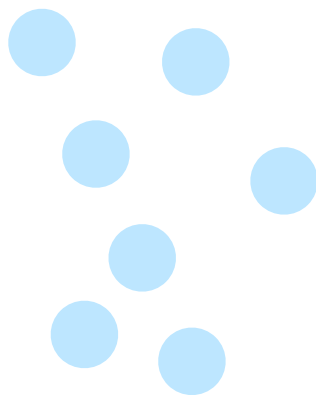
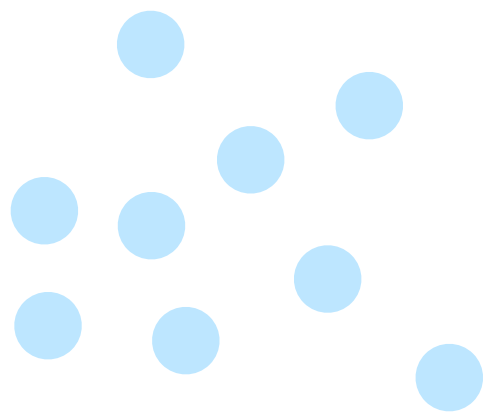


# Divisive Clustering

0. Start with everything in the same cluster

1. Use a method to split the cluster

(e.g.,  $k$ -means, with  $k = 2$ )



2. Decide on next cluster to split

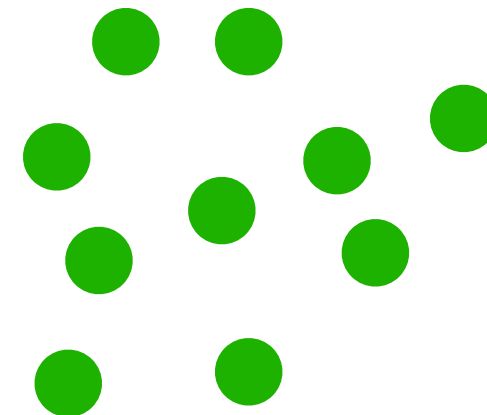
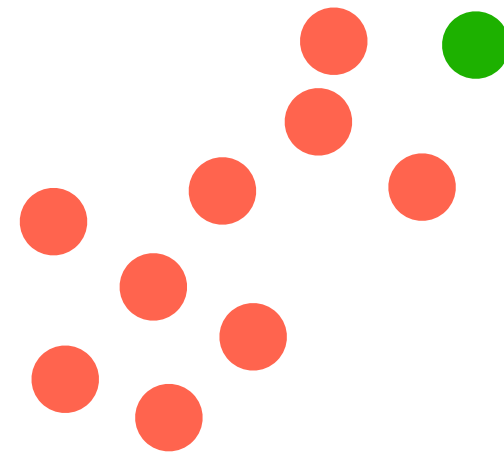
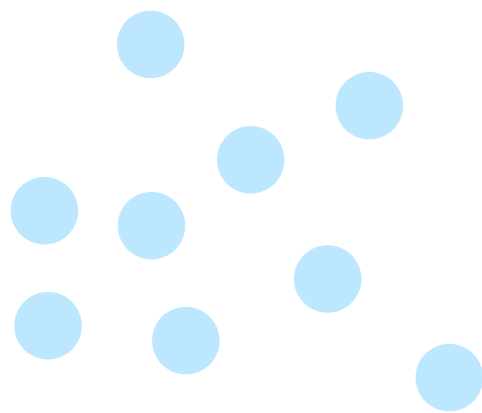
(e.g., pick cluster with highest RSS)

# Divisive Clustering

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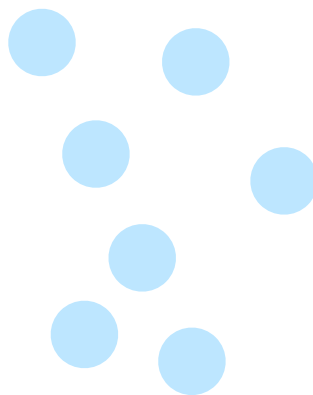
1. Use a method to split the cluster

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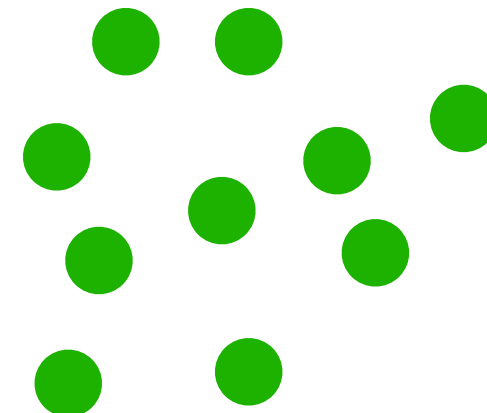
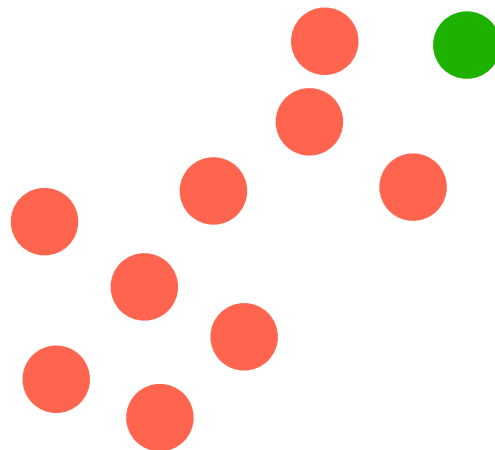
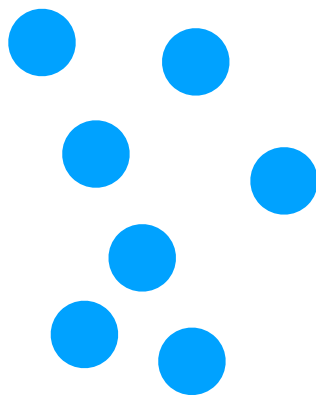
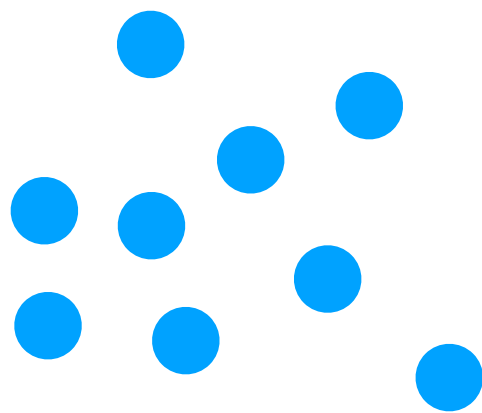


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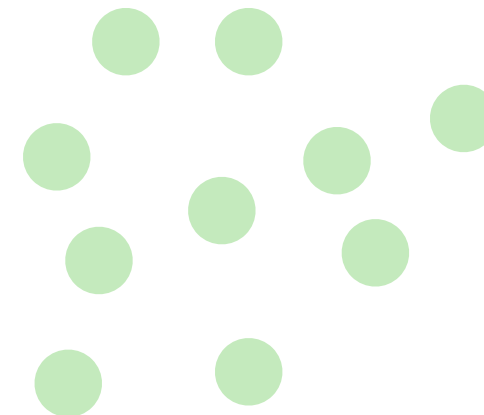
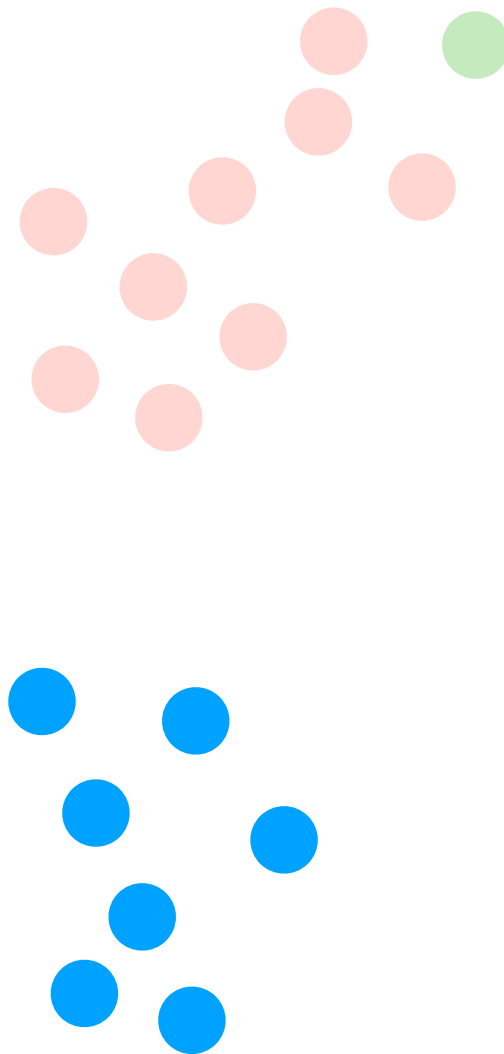
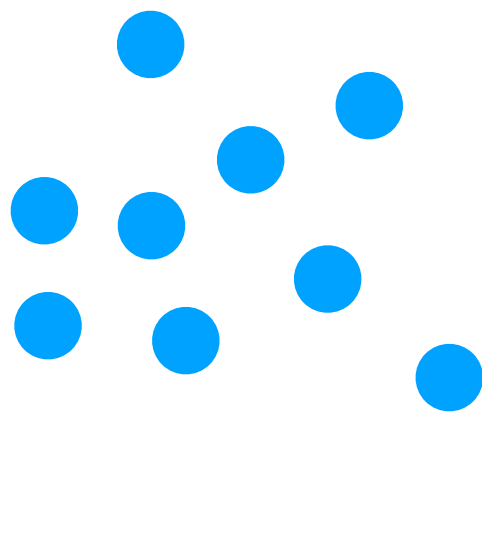
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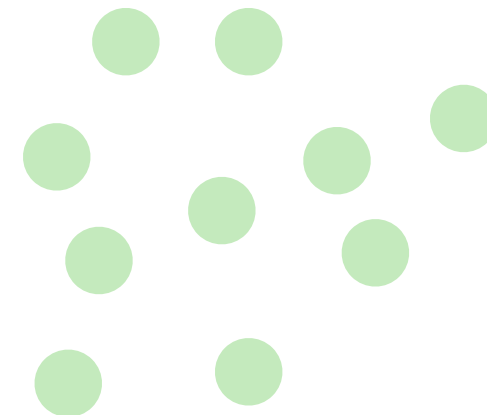
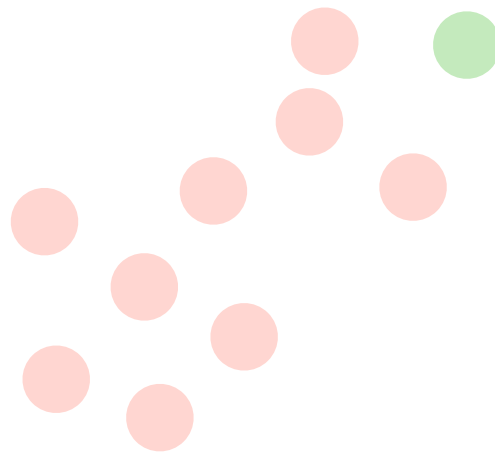
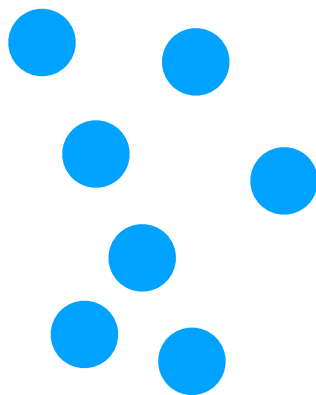
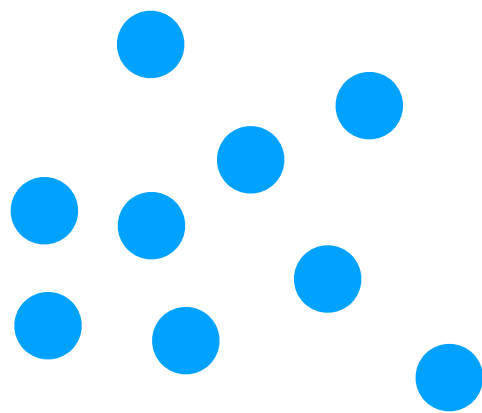
(e.g., pick cluster with highest RSS)

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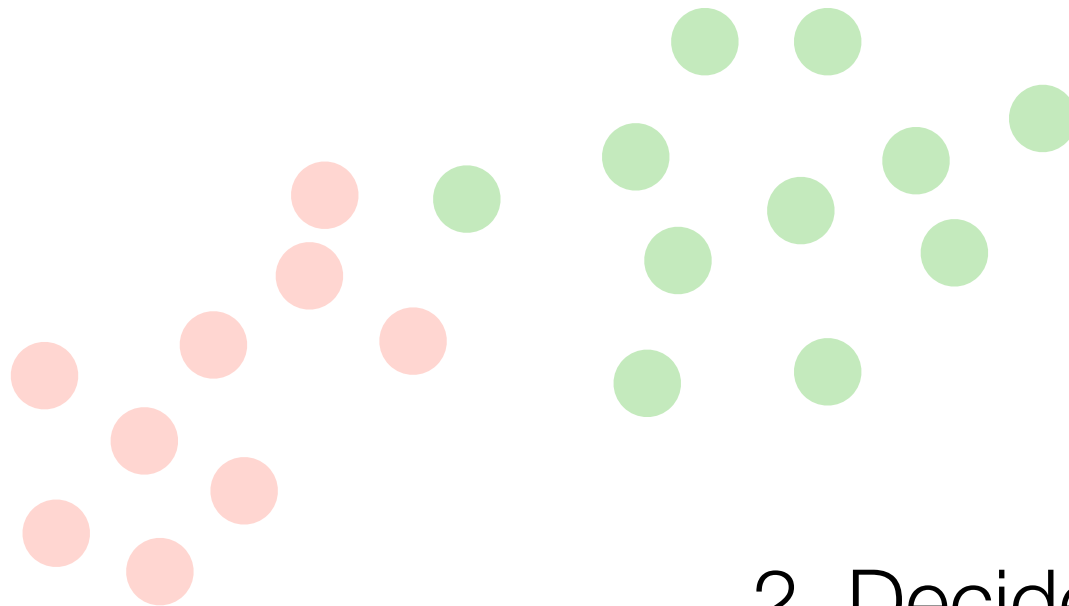
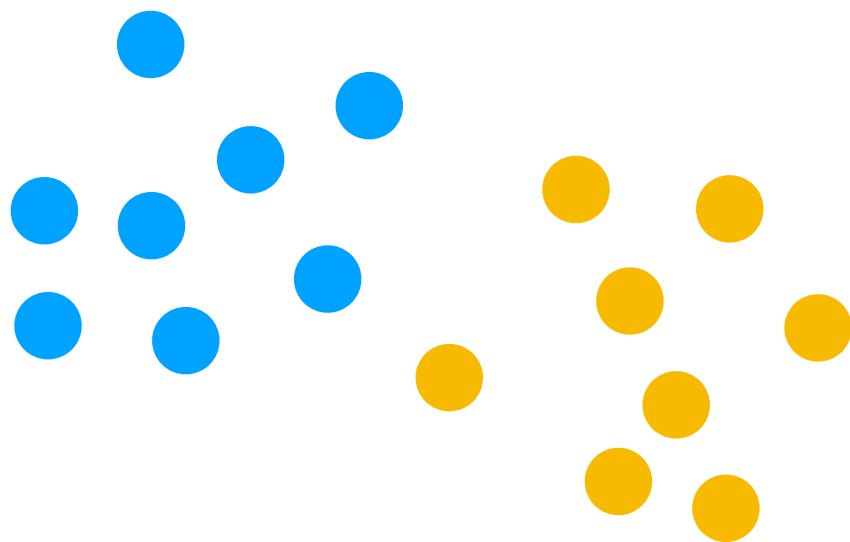
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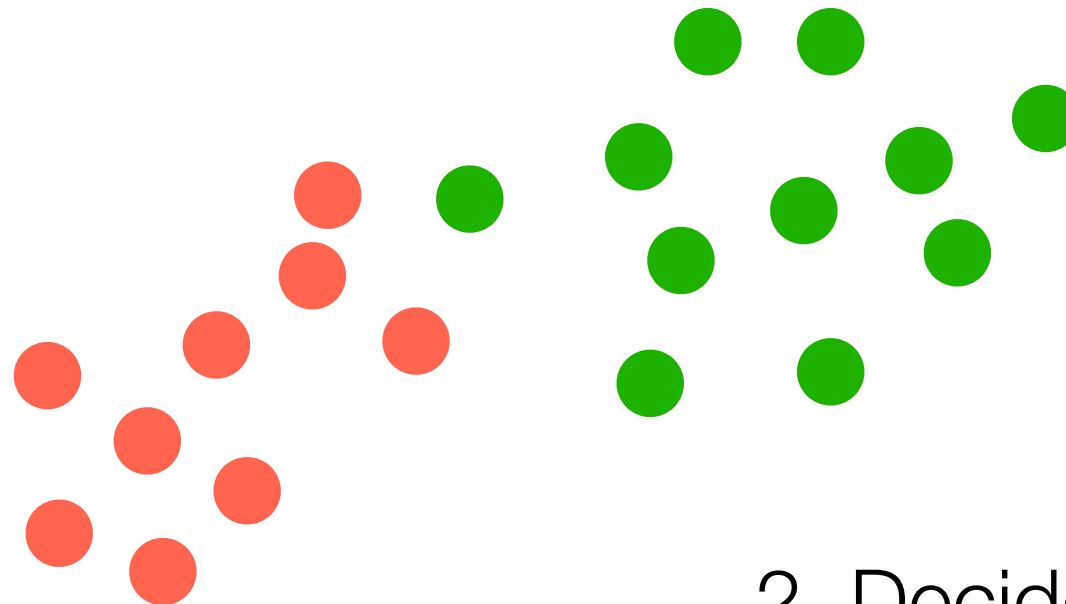
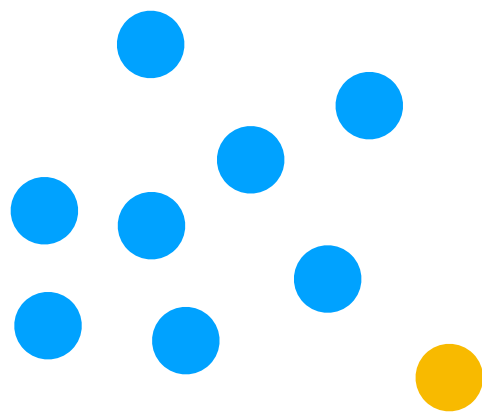
(e.g., pick cluster with highest RSS)

# Divisive Clustering

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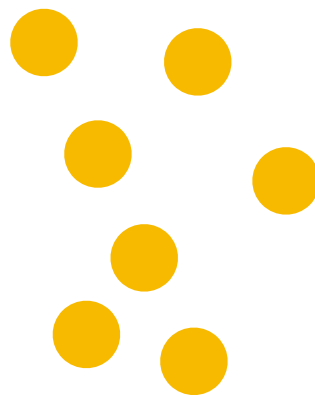
1. Use a method to split the cluster

(e.g.,  $k$ -means, with  $k = 2$ )



2. Decide on next cluster to split

(e.g., pick cluster with highest RSS)

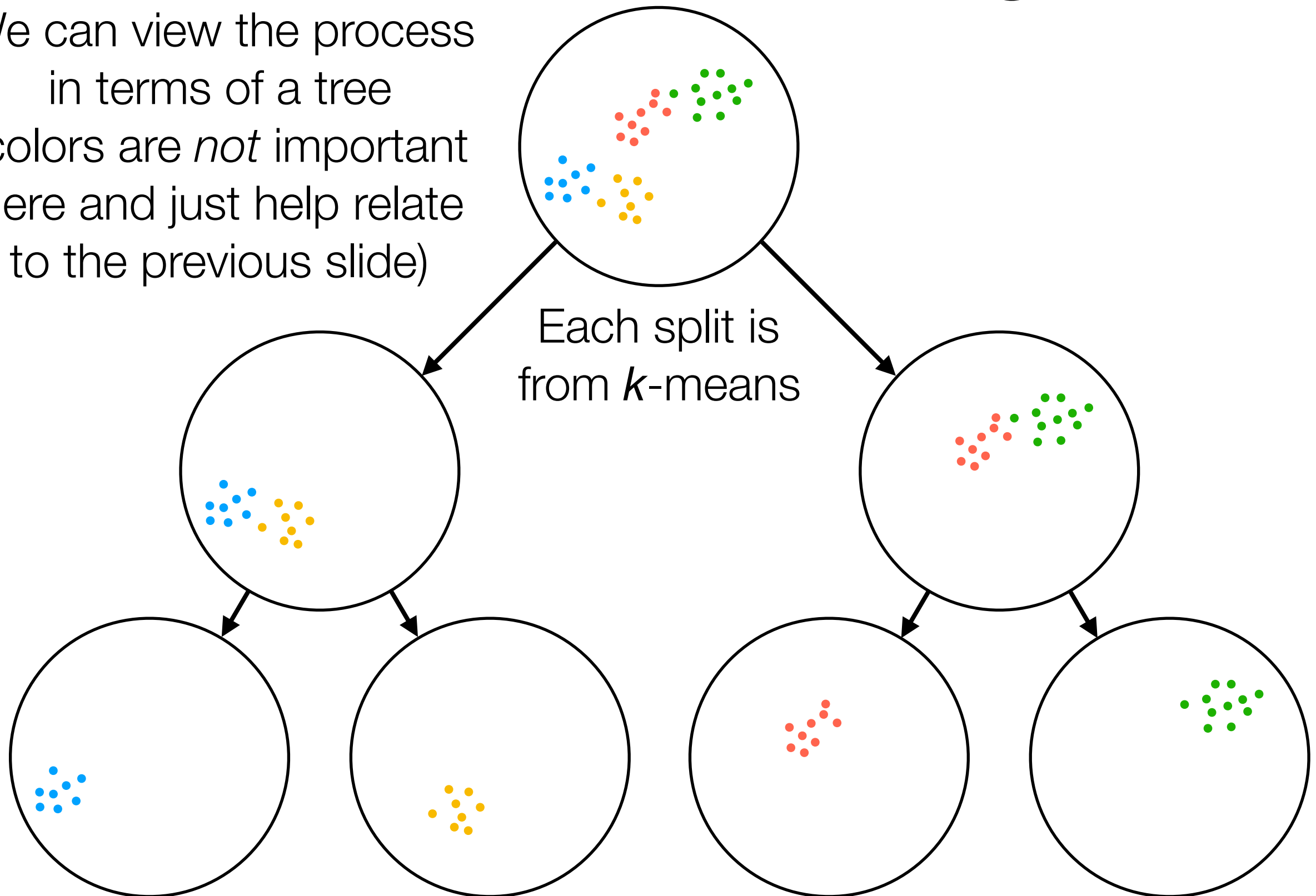


Stop splitting when some termination condition is reached

(e.g., highest cluster RSS is small enough)

# Divisive Clustering

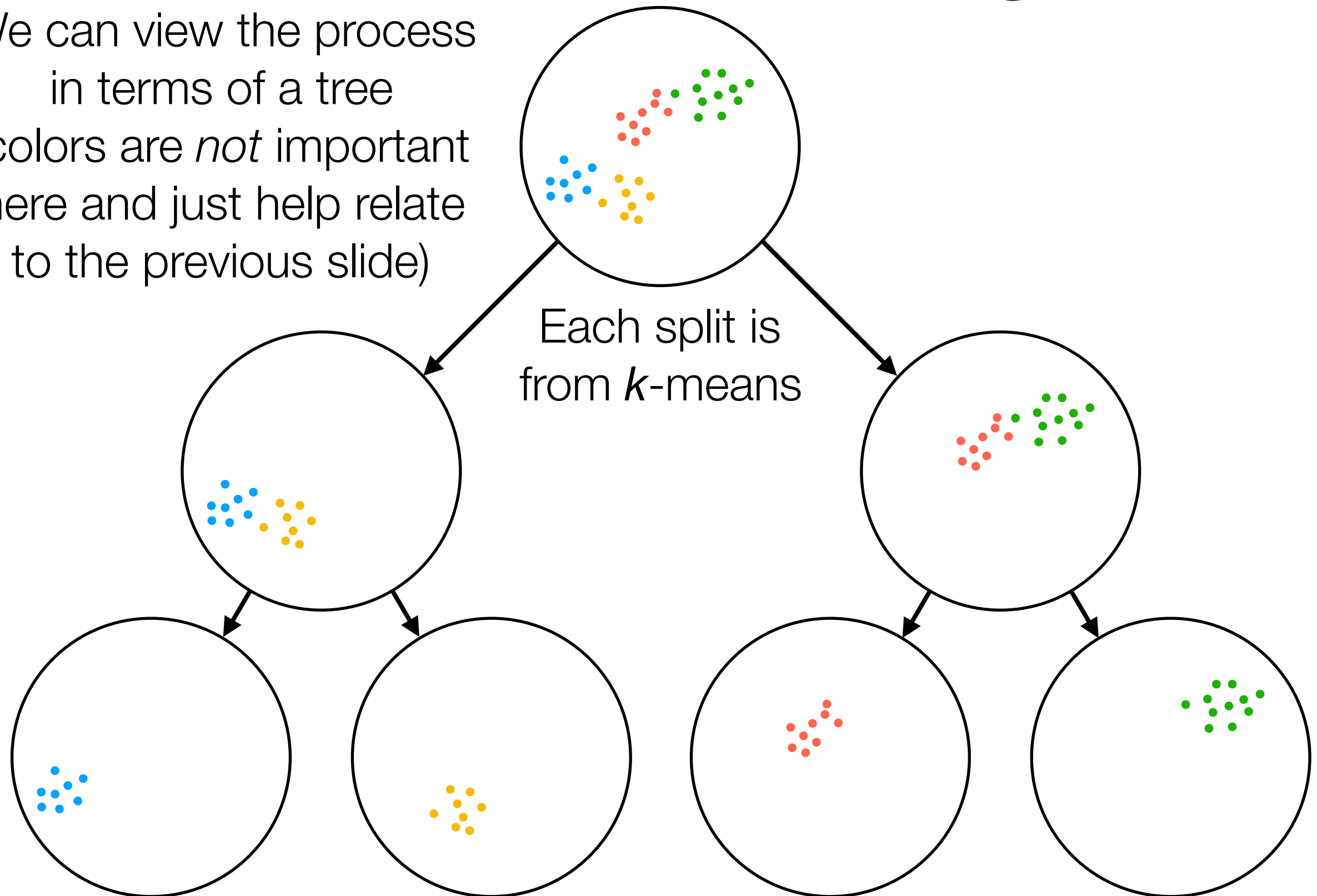
We can view the process  
in terms of a tree  
(colors are *not* important  
here and just help relate  
to the previous slide)





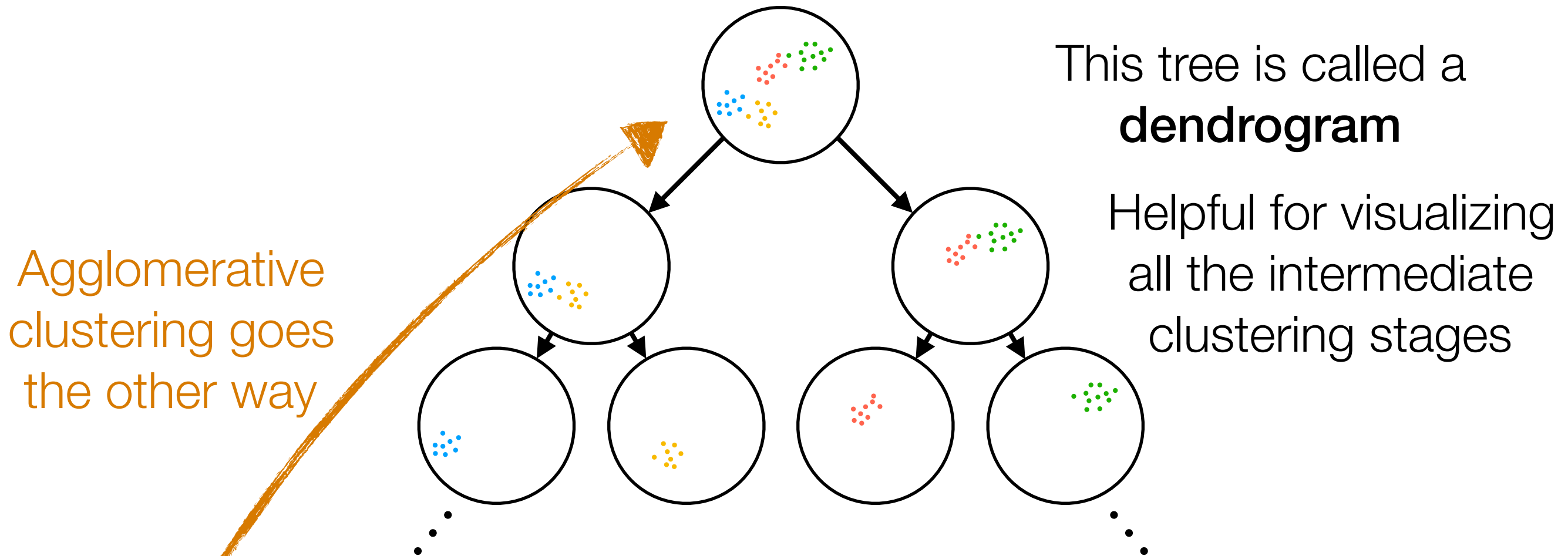
# Divisive Clustering

We can view the process  
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We could keep splitting until the leaves each have 1 point

# Divisive Clustering



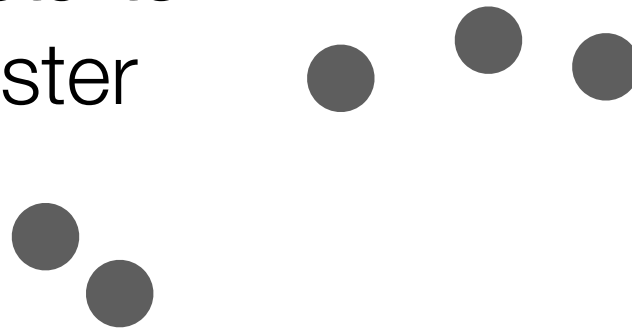
Divisive clustering uses *global* information and keeps splitting



We could keep splitting until the leaves each have 1 point

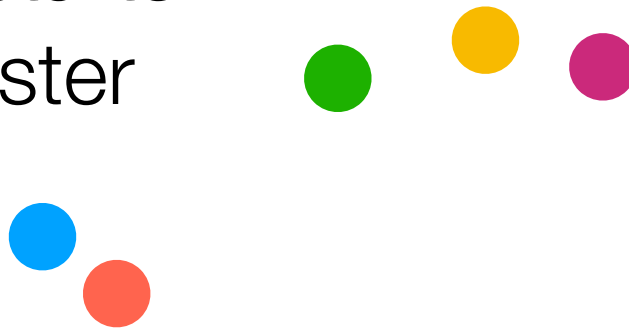
# Agglomerative Clustering

0. Every point starts  
as its own cluster



# Agglomerative Clustering

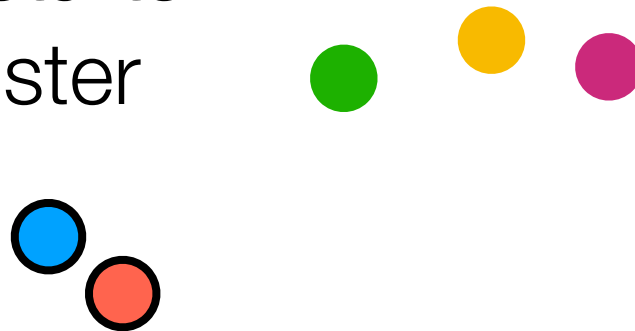
0. Every point starts  
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1. Find the “most similar” two clusters  
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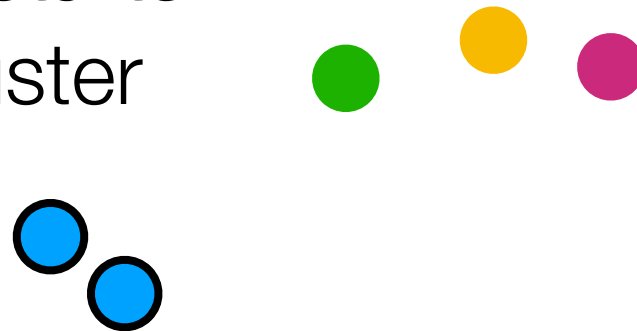


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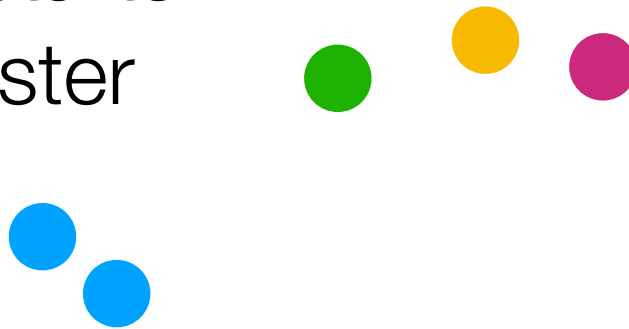


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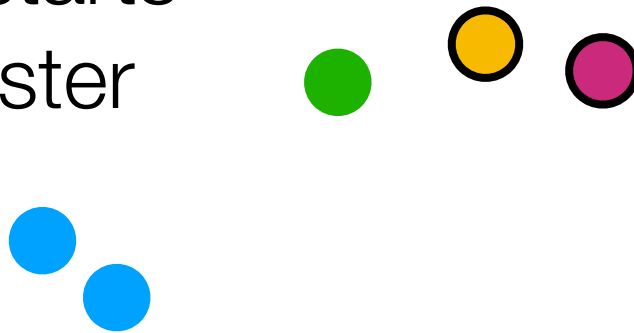


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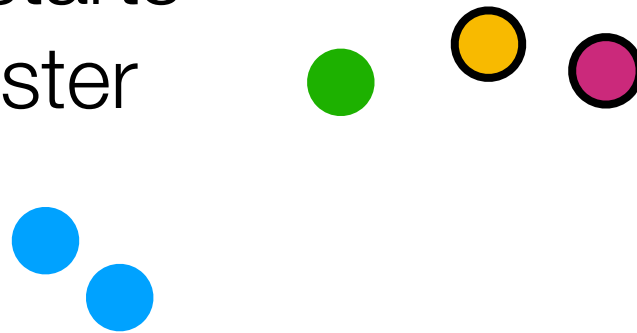
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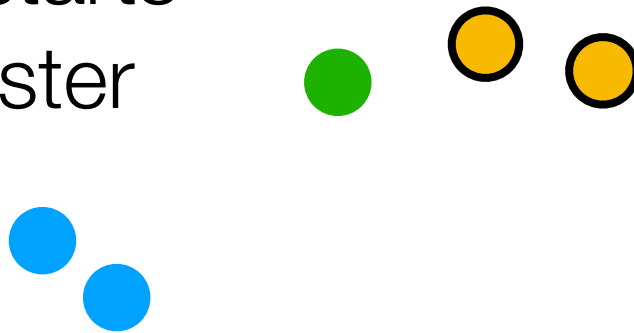


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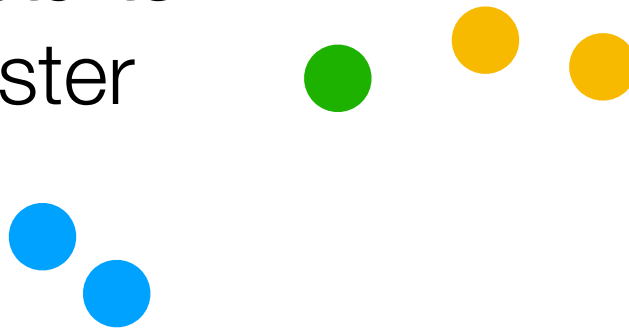


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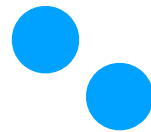
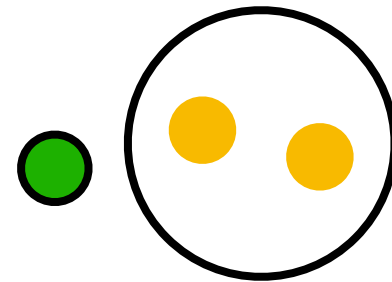


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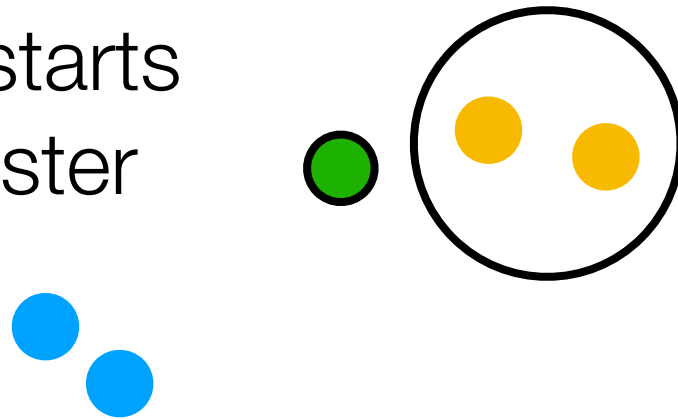


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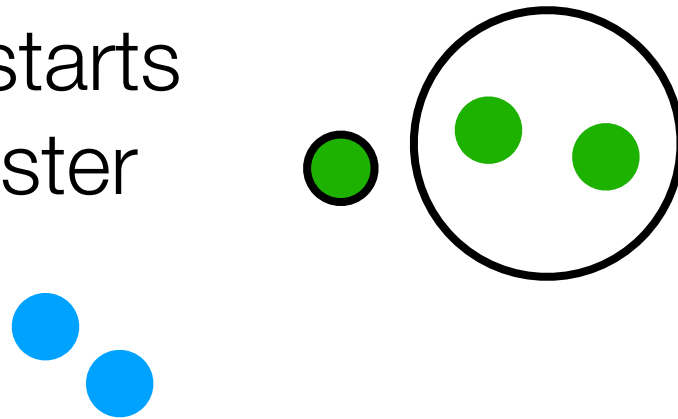


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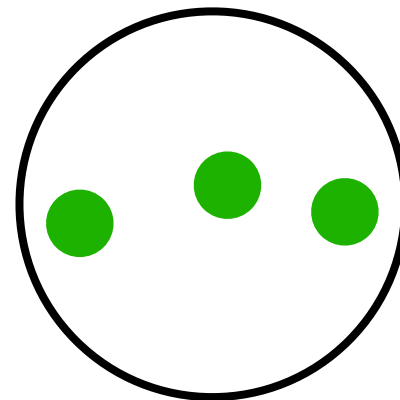
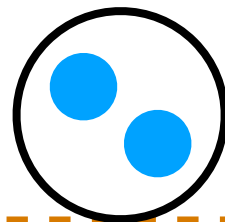


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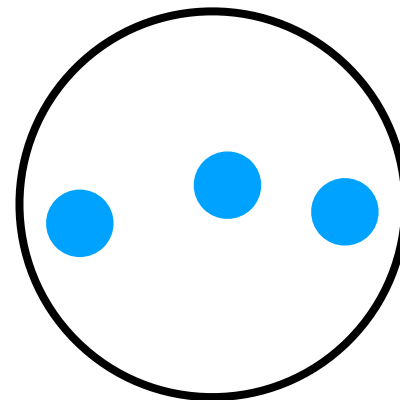
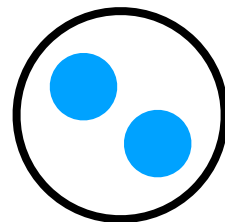


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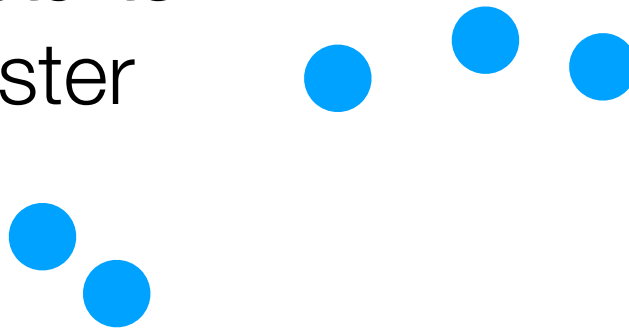
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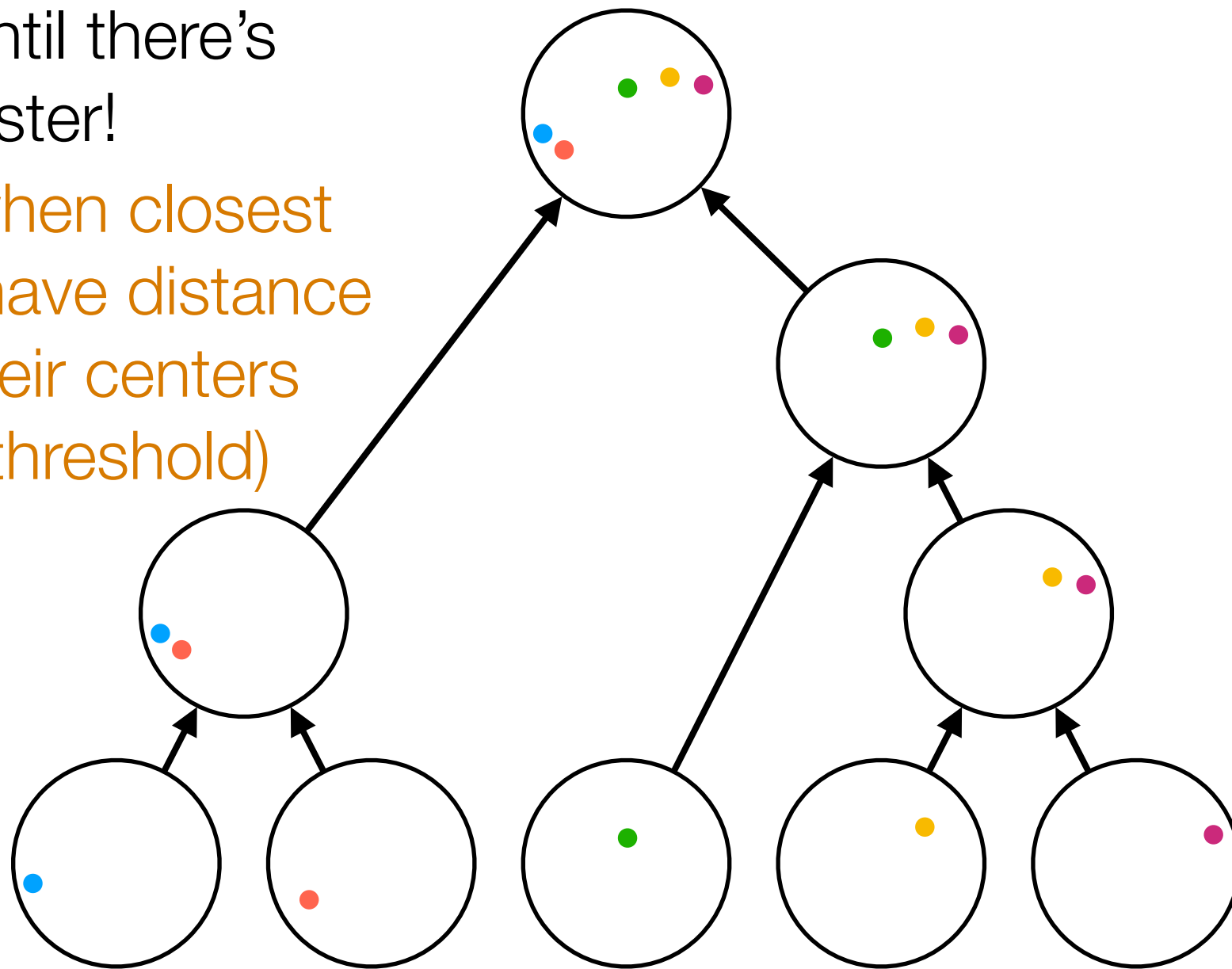
2. Merge them

# Agglomerative Clustering

Don't have to keep merging until there's 1 cluster!

(e.g., stop when closest two clusters have distance between their centers exceed a threshold)

Dendrogram



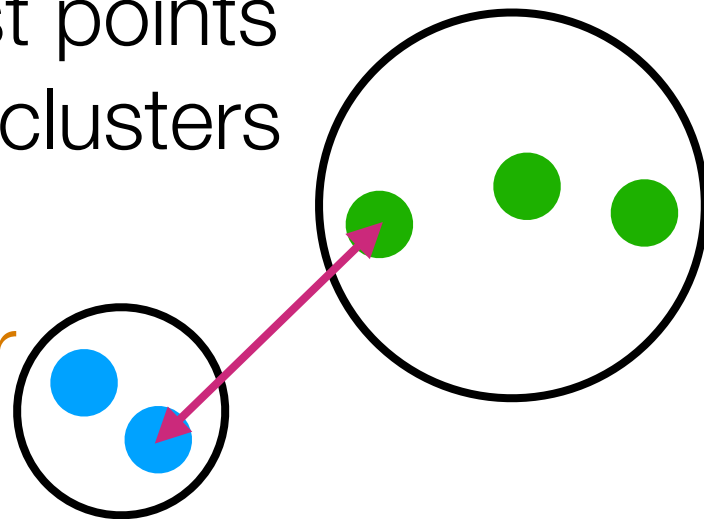
Agglomerative clustering uses *local* information and keeps merging

# Agglomerative Clustering

Some ways to define what it means for two clusters to be “close” (needed to find most similar clusters):

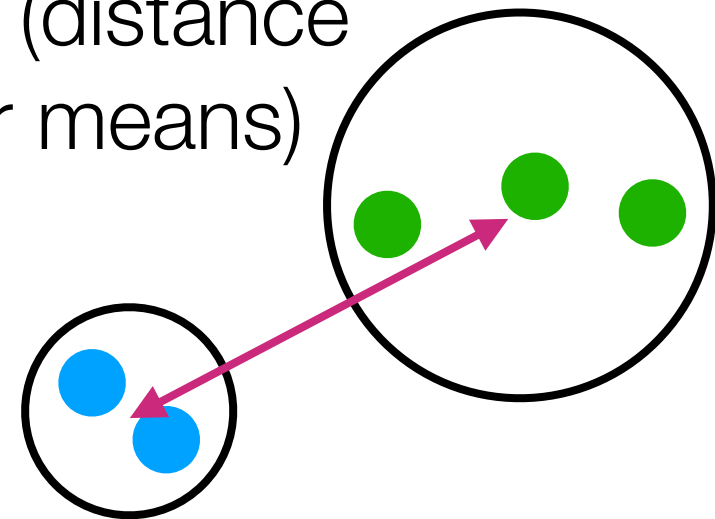
**Single linkage:** use distance between closest points across the two clusters

Can end up chaining together too many things



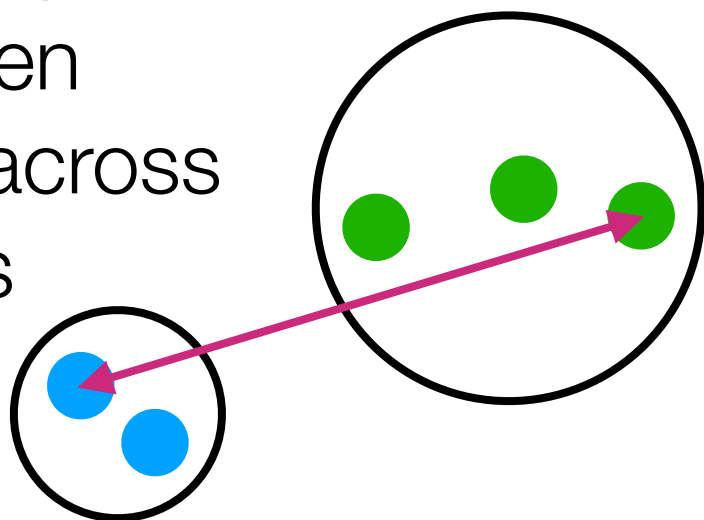
**Centroid linkage:** what we saw already (distance between cluster means)

Ignores # items in each cluster

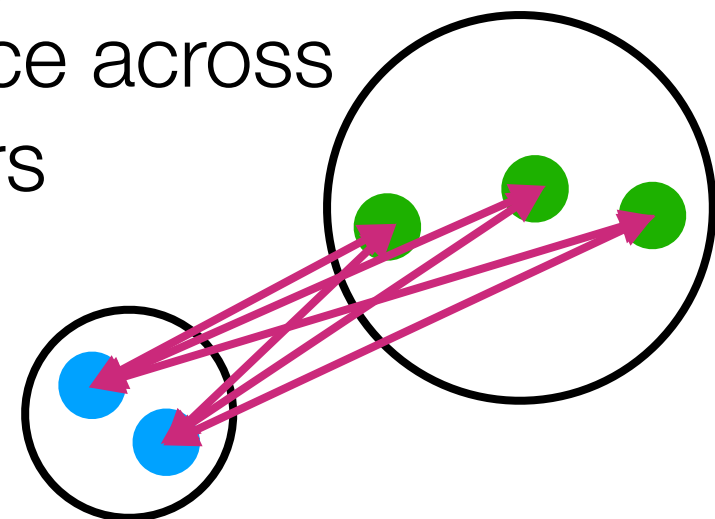


**Complete linkage:** use distance between farthest points across the two clusters

Get “crowding” behavior



**Average linkage:** use average distance across all possible pairs

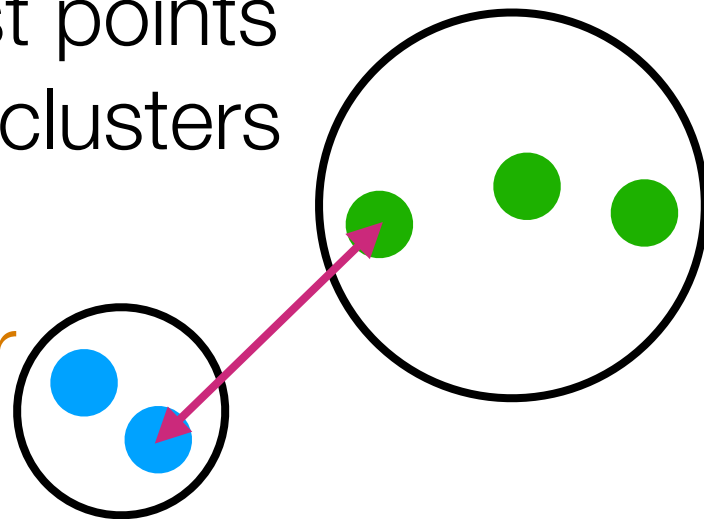


# Agglomerative Clustering

Some ways to define what it means  
(needed to find most similar clusters)

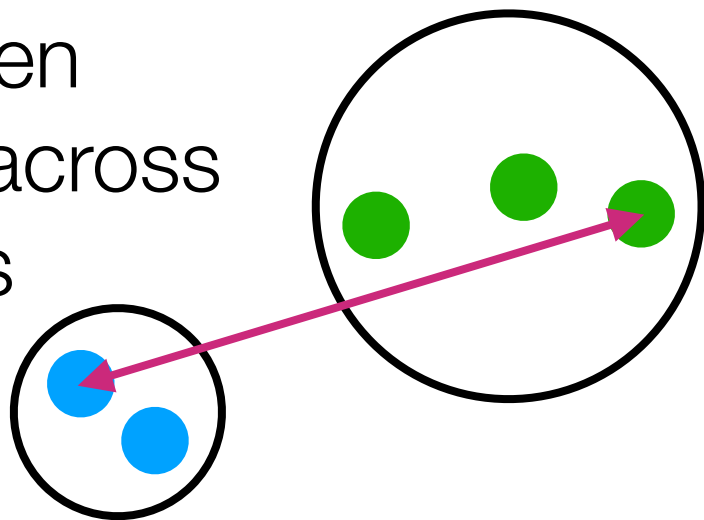
**Single linkage:** use distance  
between closest points  
across the two clusters

Can end up  
chaining together  
too many things



**Complete linkage:** use  
distance between  
farthest points across  
the two clusters

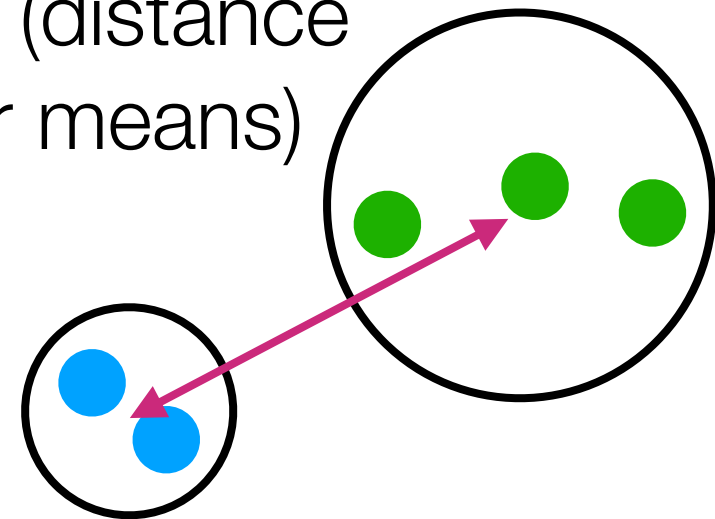
Get “crowding”  
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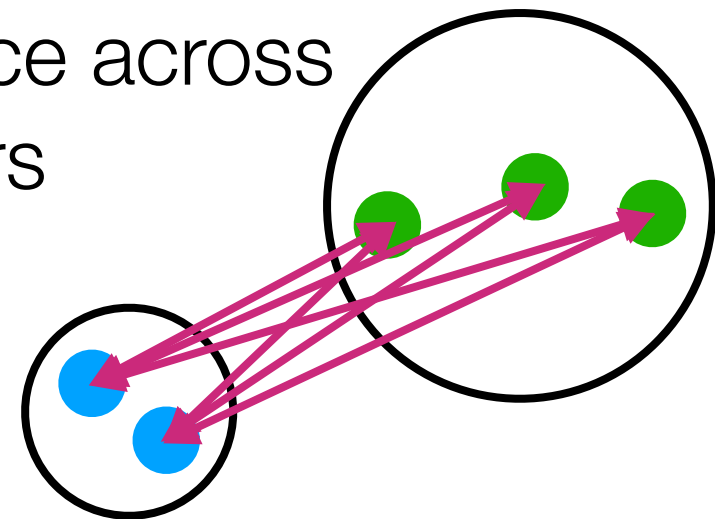
Clustering can change with  
monotonic transform of distance

**Centroid linkage:** what  
we saw already (distance  
between cluster means)

Ignores  
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**Average linkage:** use  
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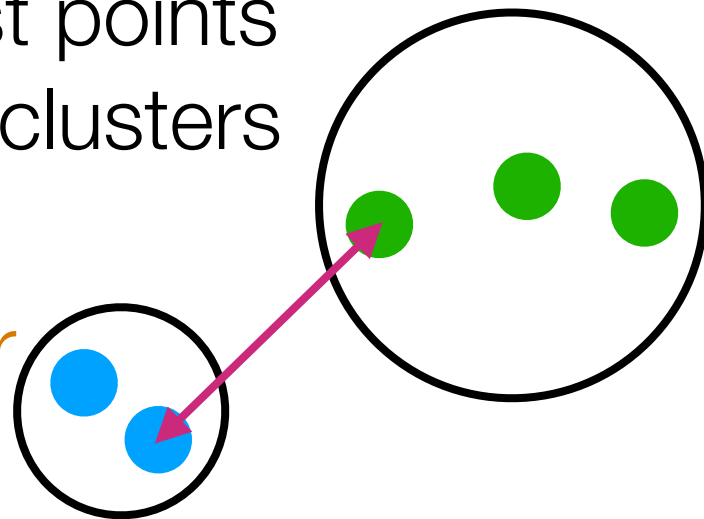


# Agglomerative Clustering

Clustering stays the same with monotonic transform of distance

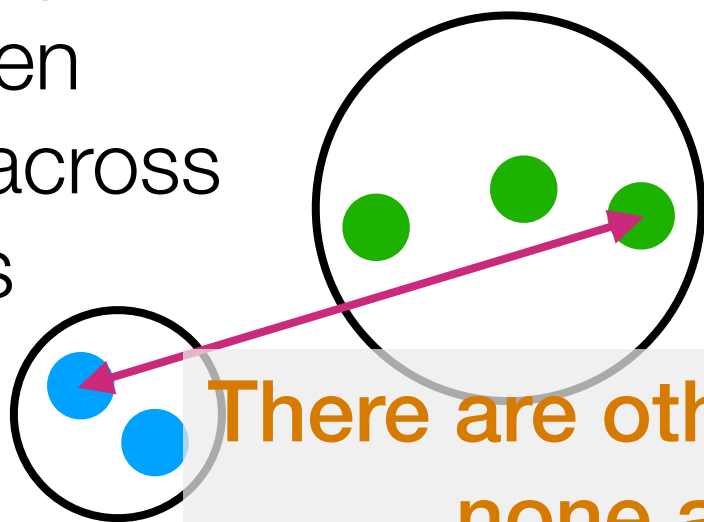
**Single linkage:** use distance between closest points across the two clusters

Can end up chaining together too many things



**Complete linkage:** use distance between farthest points across the two clusters

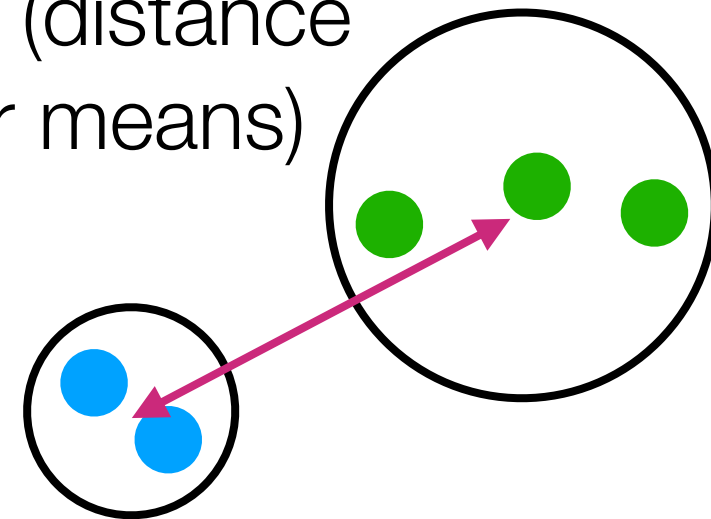
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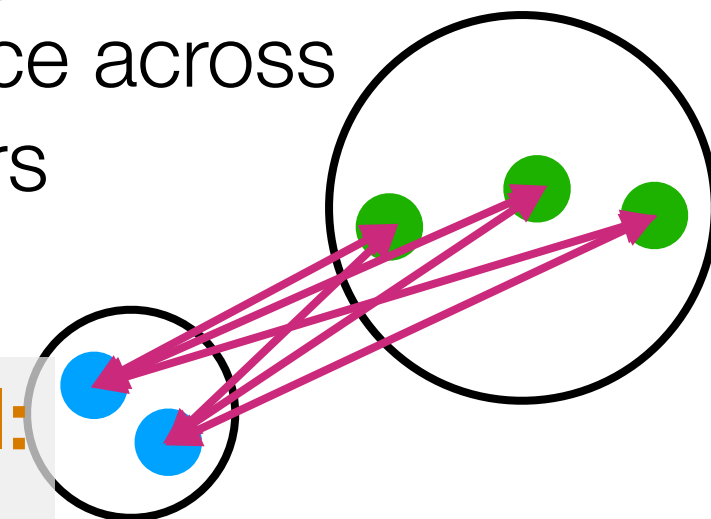
Clustering can change with monotonic transform of distance

**Centroid linkage:** what we saw already (distance between cluster means)

Ignores # items in each cluster



**Average linkage:** use average distance across all possible pairs



There are other ways as well:  
none are perfect